

Fugro Norway AS – OCEANOR Norwegian Forum for Autonomous Ships 15th June 2017





Fugro's Oceanographic Business Line

243 employees

Fugro GEOS (Wallingford, Houston, KL, Singapore, Perth)

Fugro OCEANOR AS (Trondheim, Sandnes, Madrid)

ISO 9001:2000 OHSAS 18001:1997

SEAWATCH Global Distribution





Seawatch/ Real Time Monitoring buoys







Measuring Europes wind resource

- DNVGL certified type validation
- Bankable data
- Wind speed and direction 4m 200m
- Navitus Bay Wind Park 2014
- Borssele Wind Farm Zone 2015
- Hollandse kust zuid WFZ 2016
- Baltik Srodkowy III 2017
- Hollandse kust noord WFZ 2017
- East Angla Three WFZ 2017
- Hornsea 3 Wind Farm 2017



http://offshorewind.rvo.nl

Buoy Networks - India





Buoy Networks - China





SEAWATCH Seabed Observatories









- The Seawatch Deep Sea Module:
- Ensures accurate and timely tsunami detection
- Is highly reliable low in complexity Contains only 2 parts: combined processor-pressure sensor unit & acoustic release-modem unit
- Uses state-of-the-art low-power electronics for long deployments
 Integrates with existing buoy systems
 Features built-in test functionality for system verification

- Uses two-way communication for easy interrogation and performance control
- Provides essential information for early tsunami detection

SEAWATCH Seabed Observatories





Applications Tsunami Climate change Subsea vents Deep sea biology Coral reef





Sewatch buoy applications







Buoy Autonomy



- Is a metocean buoy autonomous?
- Collects data from various sensors
- Performs multivariate analysis on collected data
- Transmits data, receives commands to execute
- Alerts when parameters are out of bounds or it is out of position
- Starting and stopping instruments based on power available
- Starting and stopping fuelcell charging
- Provides position and observations over AIS to nearby vessels
- However, no propulsion or GPS waypointing

On-going Projects

- eFarled Wavescan Implementation of AIS AtoN Hydrological Message 8 broadcasted to Kystekspressen Brekstad – Kristiansund
- Hellenic Center of Marine Research Wavescan + AIS AtoN Hydrological msg 8 broadcast to ferry crossings
- Statoil project Troll Wavescan as 4G gateway to subsea resident ROV streaming video and providing control. Supply vessel does not need to stay while ROV operates, drop and leave.

Possibilities

- Buoy as a hub for charging, data upload/download
- High precision GPS positioning on buoy(s) with acoustic positioning subsurface relative to surface buoy

UGRO

Challenges



- Rough conditions
- Autonomous vessels are typically small with less/no freeboard
- OCEANOR has 30 years experience what works in which conditions – Sea states, currents, winds







Thank you for your time

Vegar Neshaug Fugro Norway AS

NFAS Trondheim June 2017