



## **GNSS PPP (Precise Point Positioning)**

A New Development for High Precision Navigation and Positioning

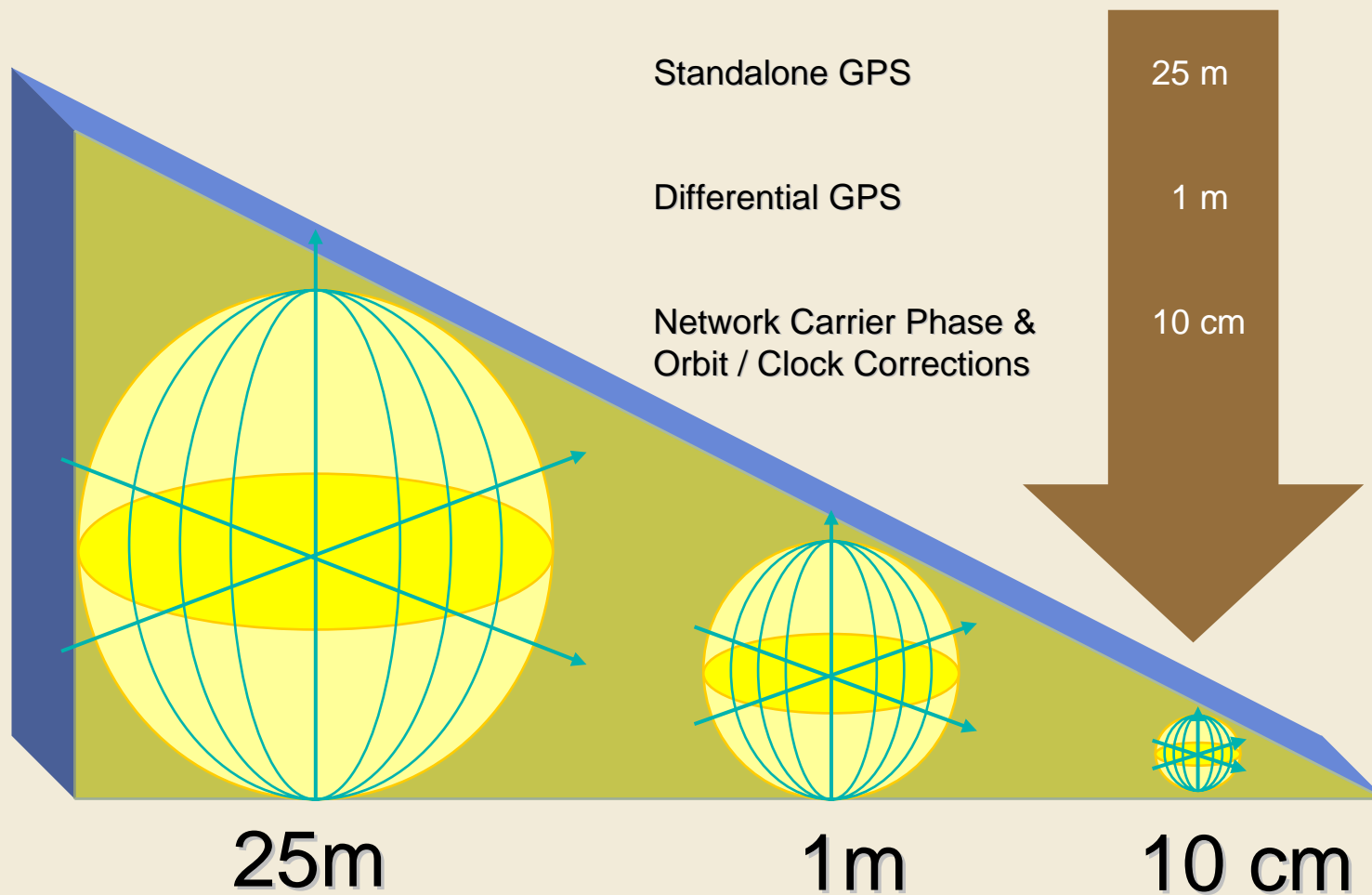
John Vint, Survey Manager, Fugro Survey AS  
NNF – E-Nav Conference, Bergen, 6 March 2009



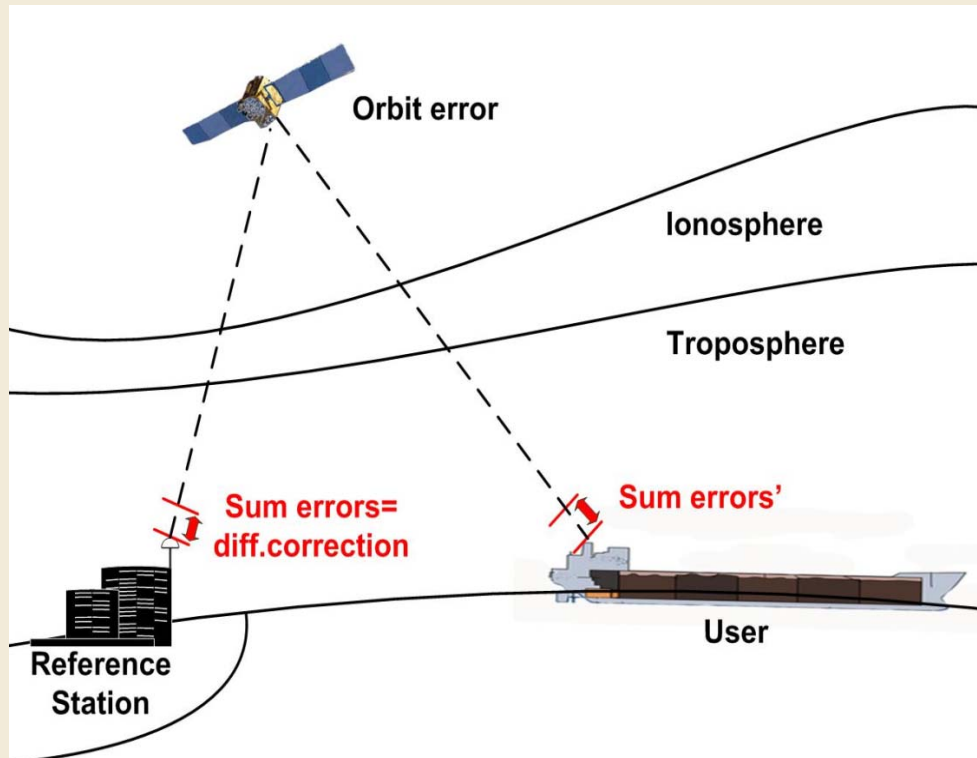
- What is GNSS PPP ?
- GPS Based High Precision Systems.
- Return of GLONASS.
- Fugro G2 Development.
- Advantages of Combined GNSS Systems.
- Products, Trials and Results.
- What does the Future have in store ?

# GNSS (Global Navigation Satellite Systems)

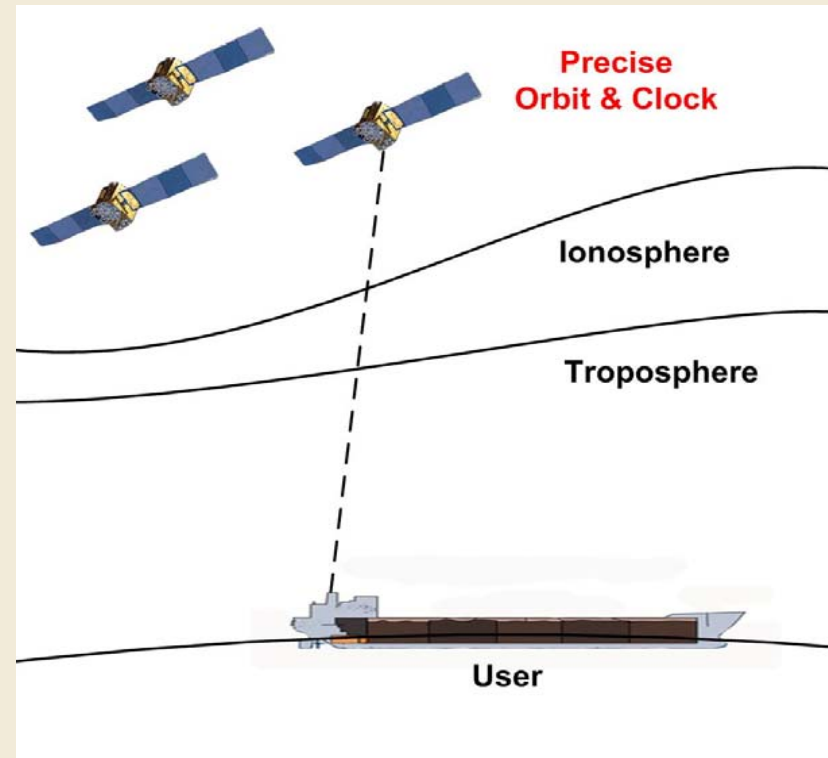


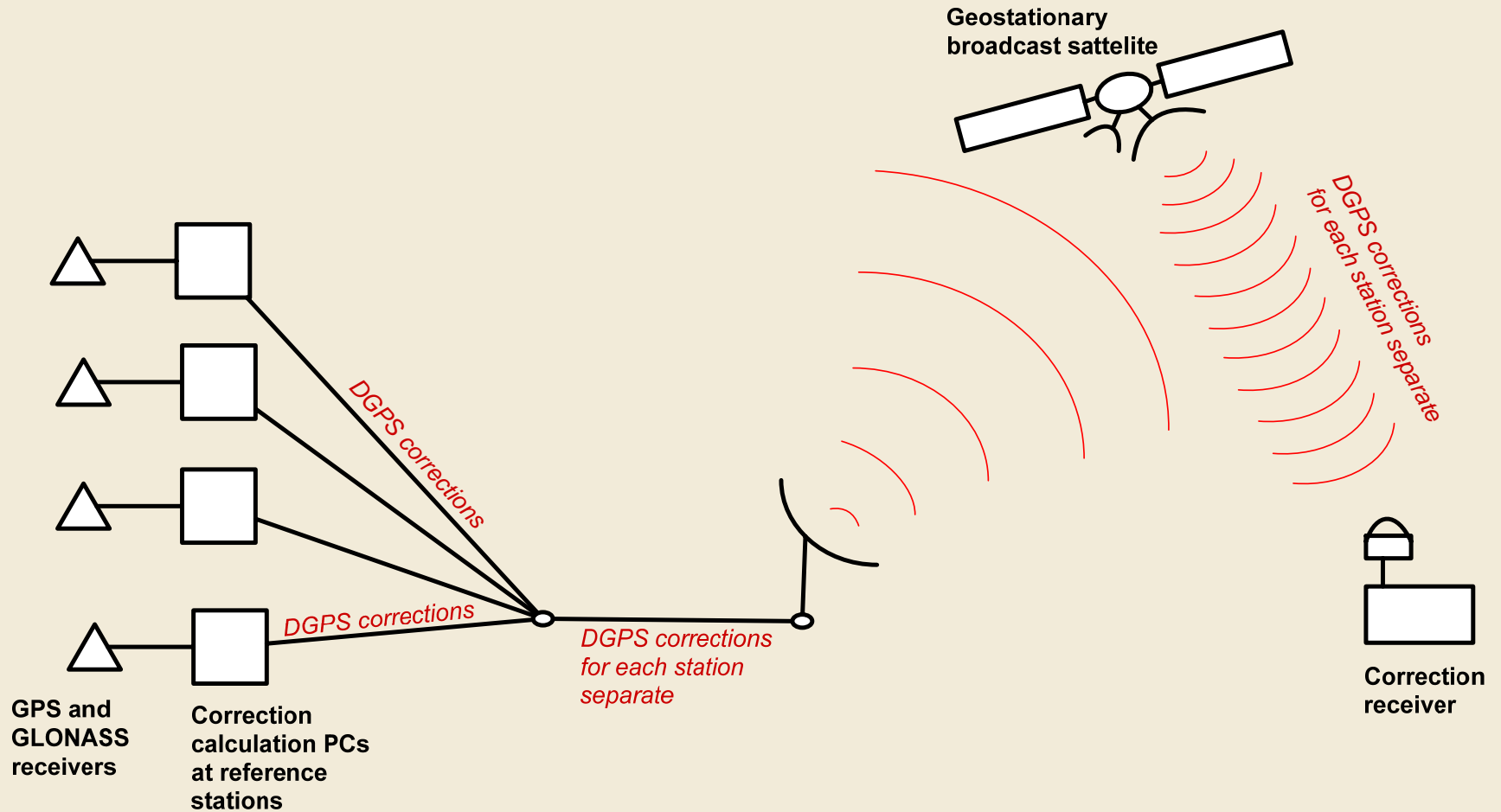


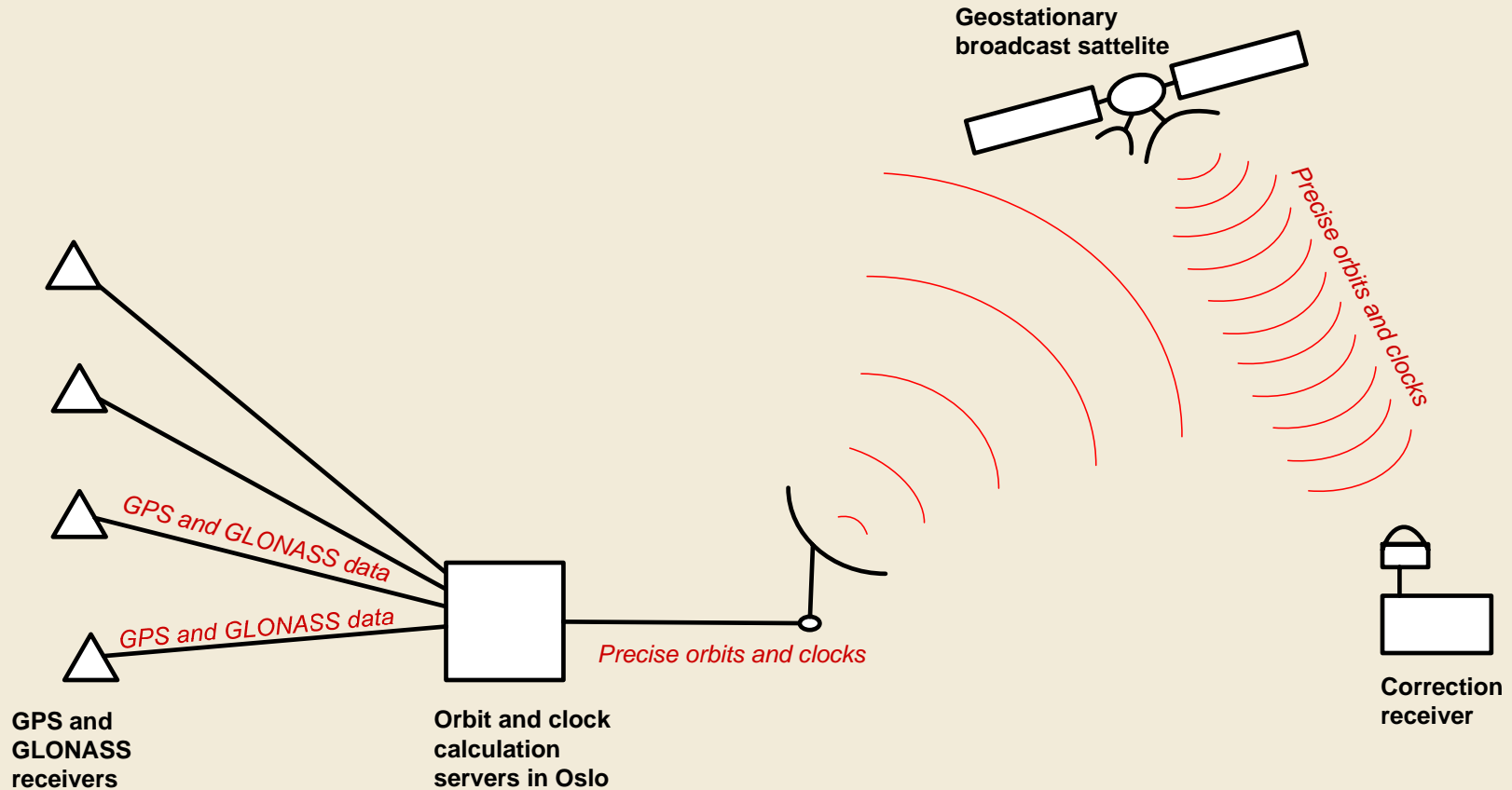
## Differential (DGPS)



## Orbit and Clock











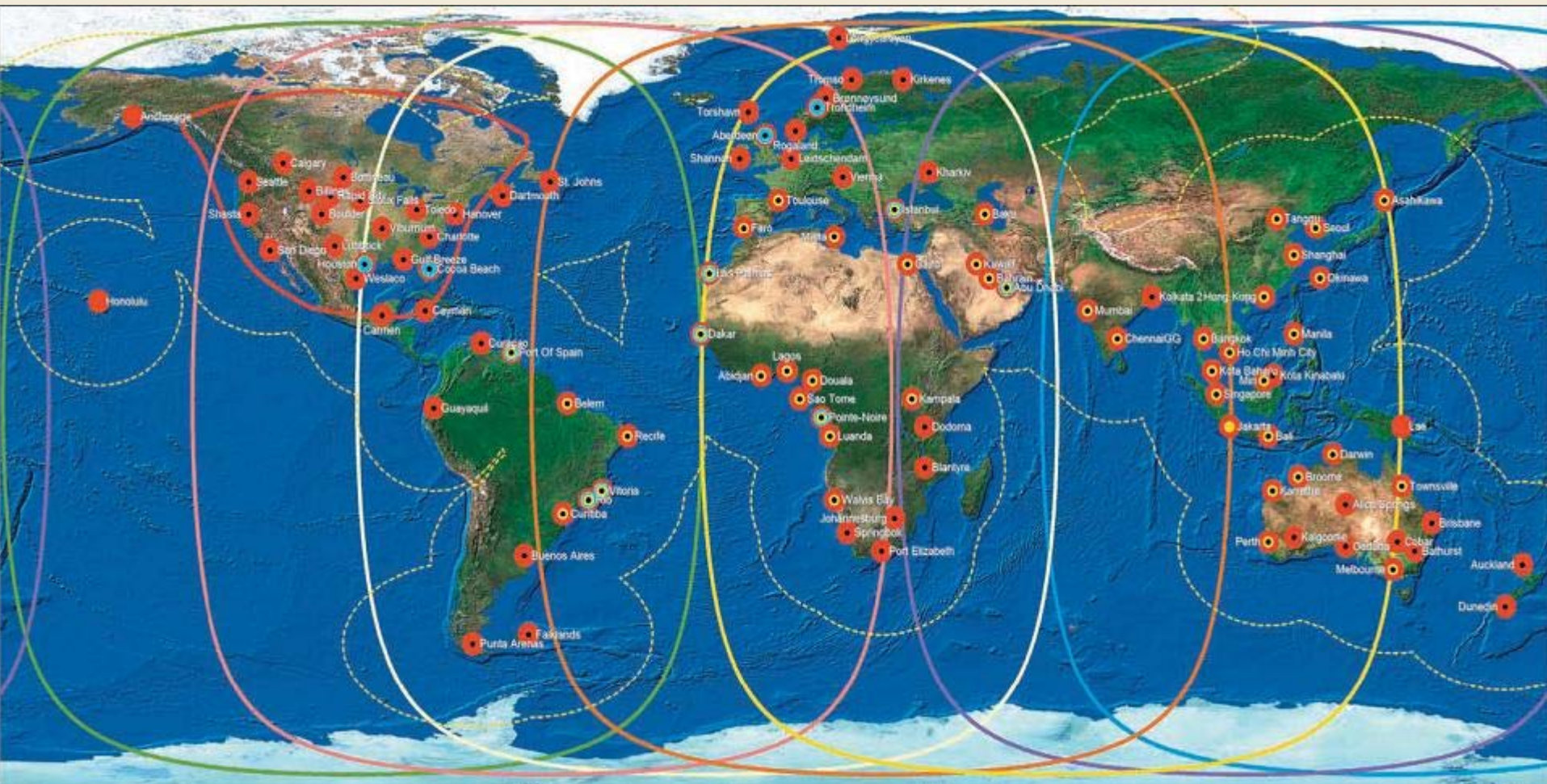
# GPS Based High Precision Systems







# Fugro Reference Station Network and Broadcasts



Index    ● Single Freq.    ● Dual Freq.    ● Glonass    ● HP

AM-SAT

AMSC

AORW-H

AORE-H

EA-SAT/AF-SAT

IOR-H

AP-SAT

OC-SAT

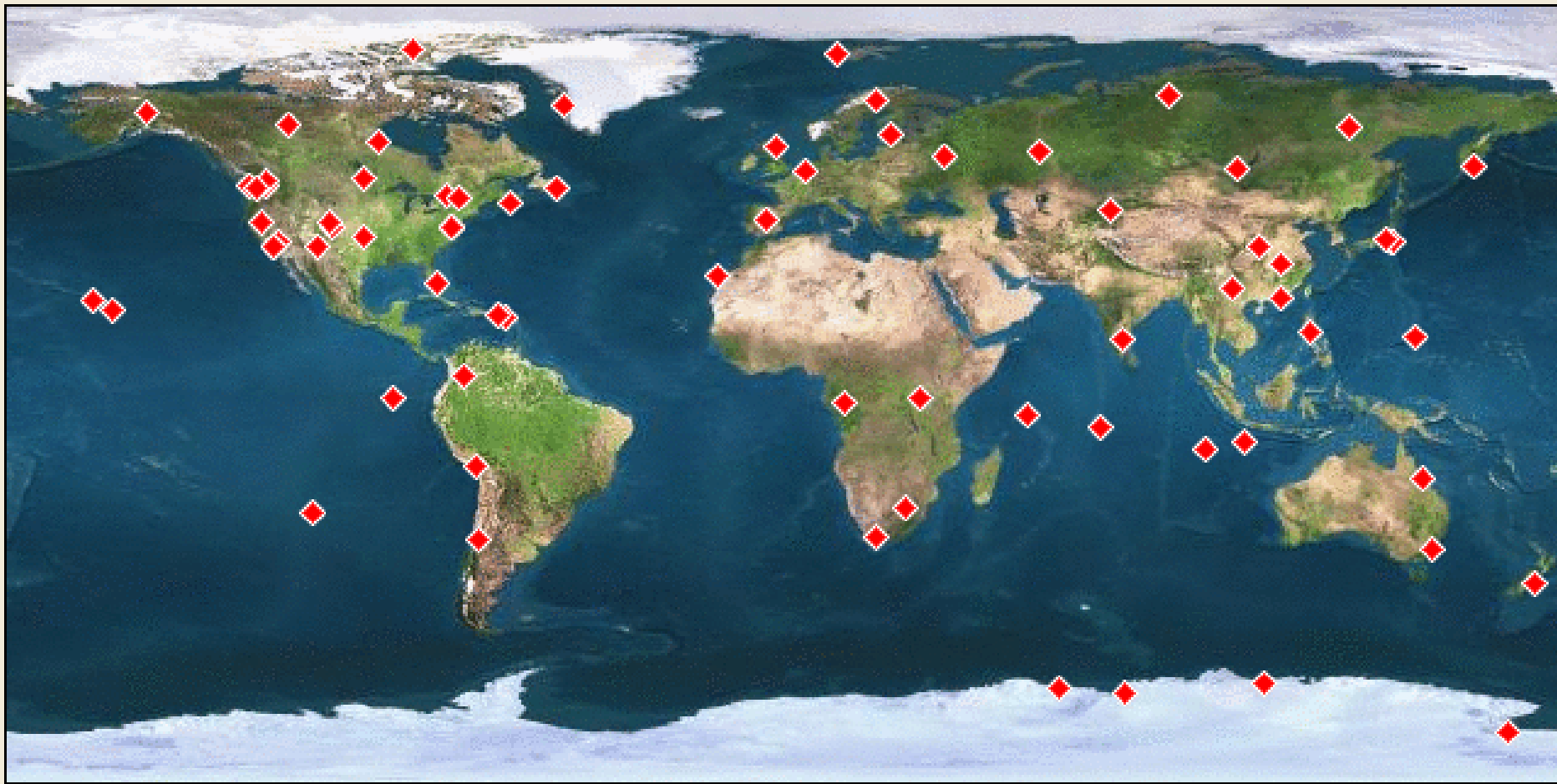
2000 Km



- All elements developed and implemented by Fugro
- Uses correction data from Fugro's proprietary reference station network.
- Multi Reference Network Carrier Phase positioning computation.
- Dual Frequency
- Fugro Starfix.HP in HP Mobile and StarPack software.
- ca 30 minutes convergence time to full accuracy
- 10 cm accuracy (2 sigma) assuming a reference station within 500 km



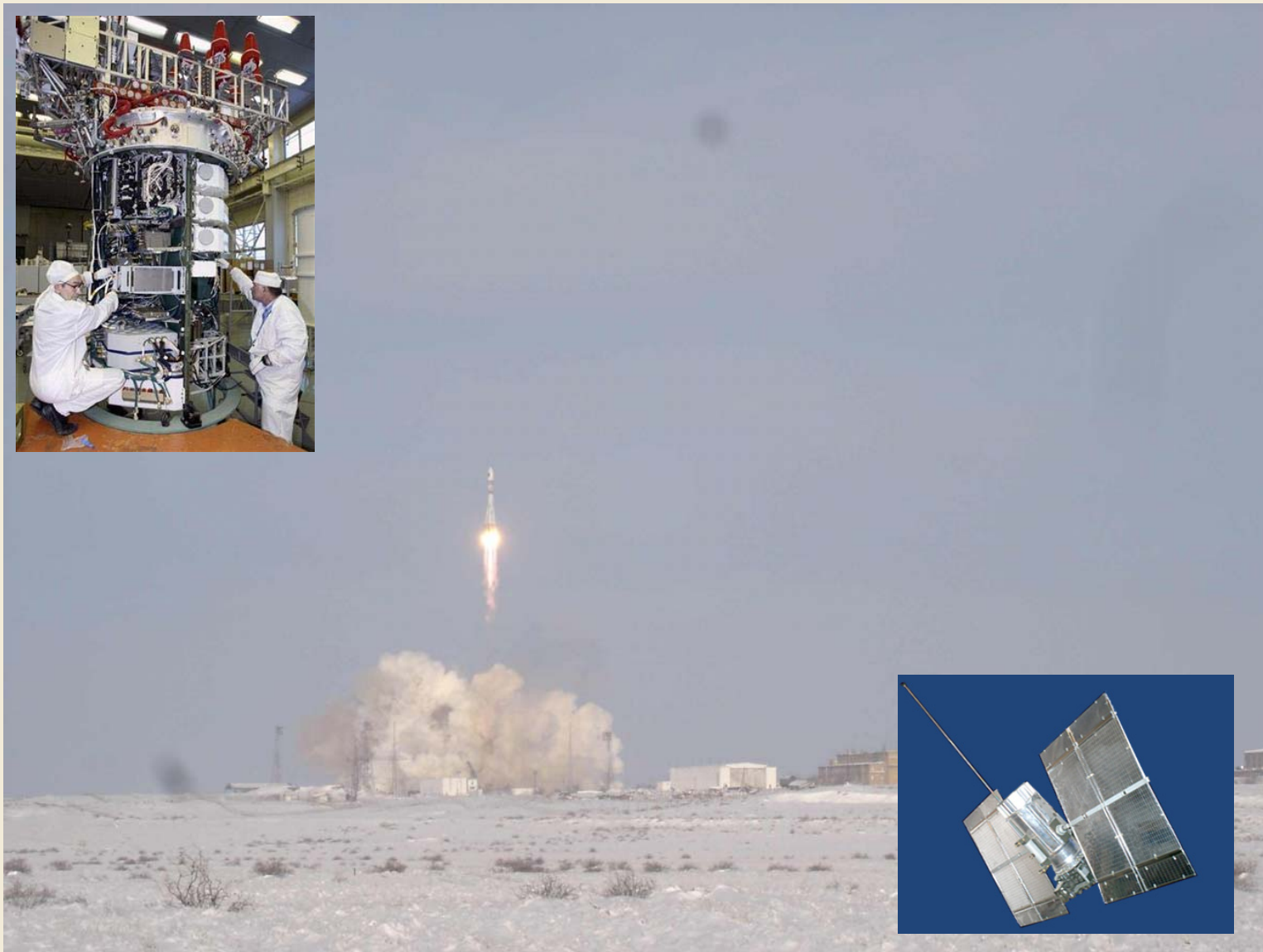
# NASA / JPL Tracking Stations





- Hybrid system – Signals purchased from NASA / JPL, all other elements developed by Fugro
- Uses NASA / JPL managed reference stations
- Orbit and Clock “Global State Space” position computation.
- Dual Frequency system.
- MultiFix5 software.
- ca 30 minutes convergence time to full accuracy
- 10 cm accuracy (2 sigma) almost independent of location.







Russia

## Putin orders completing GLONASS satellite system before 2008

14:35 | 26/12/2005



MOSCOW, December 26 (RIA Novosti) - Russian President Vladimir Putin said Monday that he wanted the GLONASS global navigation satellite system ready before 2008.

"The GLONASS system should be created before 2008, as it was originally planned," Putin told government members. "We have the possibility. Let us see what can be done in 2006-2007."

Defense Minister Sergei Ivanov said three new satellites had been successfully put into orbit Sunday to expand the navigation system.

He said 19 out of 24 GLONASS satellites were currently in orbit.

"I am convinced that by 2008, all the 24 satellites will be in orbit as part of the GLONASS federal target program," Ivanov said.

The president noted however that the satellites should be put into orbit earlier.

The first GLONASS satellite was put into orbit in 1982, but the system was officially launched in 1993.

[send by e-mail](#) >>

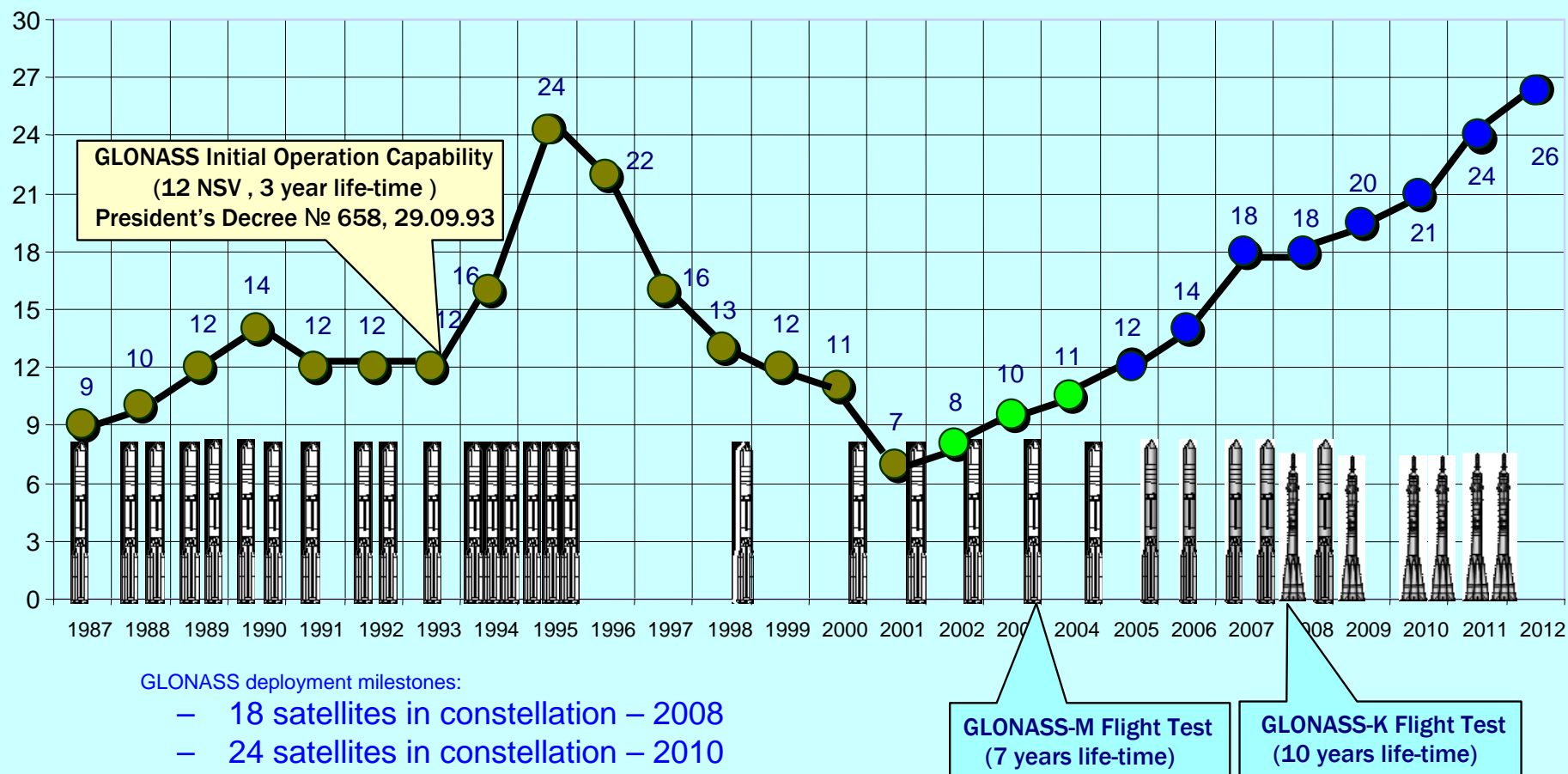
[back to main page](#) >>

## Deployment Milestones:

- 14 satellites – 2007
- 20 satellites – 2008
- 24 satellites – 2009

## Performance Comparable to GPS by 2009

<http://en.rian.ru/russia/20051226/42709745.html>







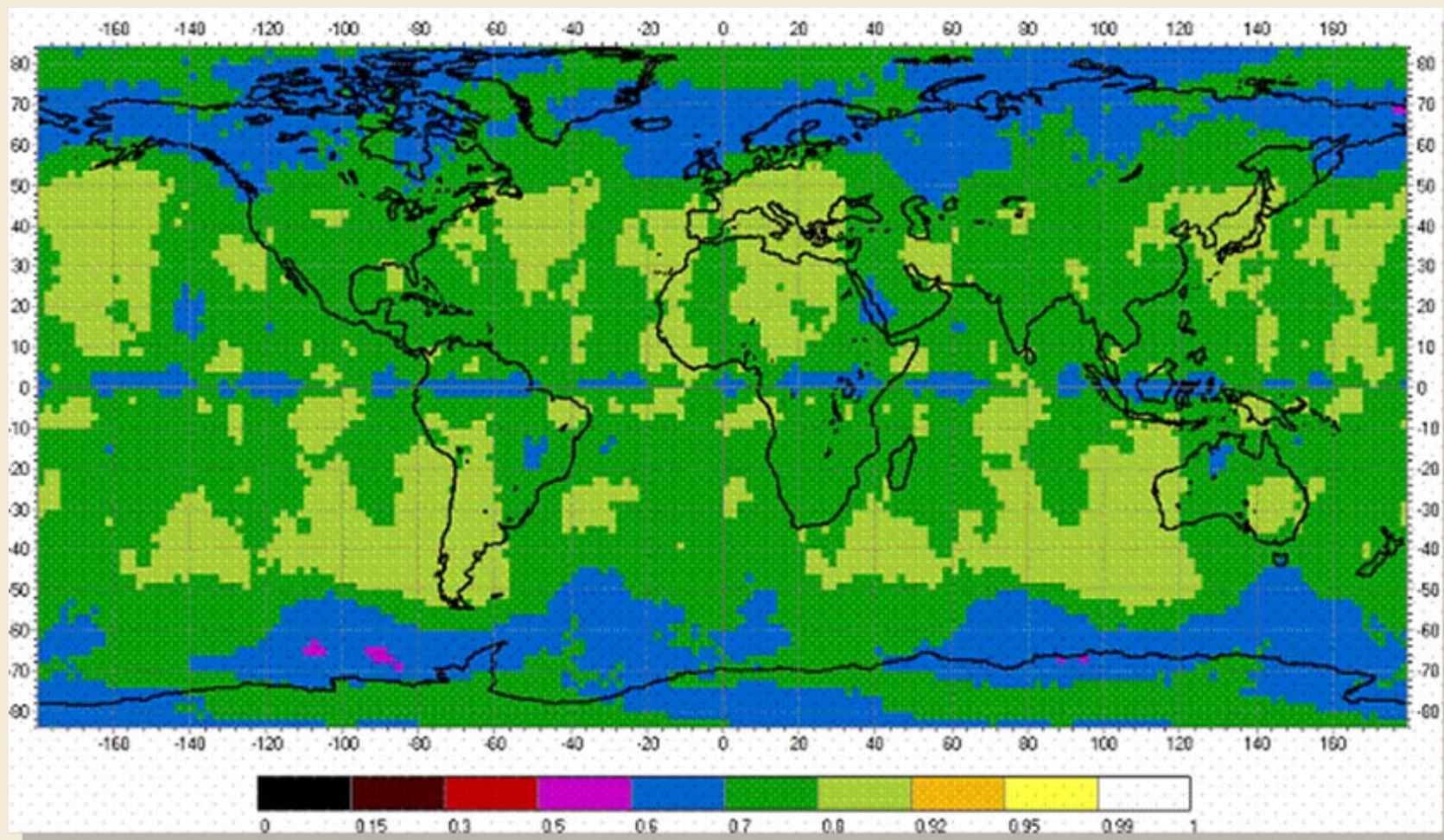
# 16 of 17 Satellites Available

**GLONASS Constellation Status at 01.12.2008 based on both the almanac analysis and navigation messages received at 10:00 01.12.08 (UTC) in IAC PNT TsNllmash**

Orb. pl.	Orb. slot	RF chnl	# GC	Launched	Operation begins	Operation ends	Life-time (months)	Satellite health status		Comments
								In almanac	In ephemeris (UTC)	
I										
	4	06	795	10.12.03	29.01.04		59.8	+	+ 08:45 01.12.08	In operation
	6	01	701	10.12.03	08.12.04		59.8	+	+ 10:15 01.12.08	In operation
	7	05	712	26.12.04	07.10.05		47.2	+	+ 10:15 01.12.08	In operation
II	9	-2	722	25.12.07	25.01.08		11.2	+	+ 06:44 01.12.08	In operation (L1 only)
	10	04	717	25.12.06	03.04.07		23.2	+	+ 08:15 01.12.08	In operation
	11	00	723	25.12.07	22.01.08		11.2	+	+ 09:47 01.12.08	In operation
	13	-2	721	25.12.07	08.02.08		11.2	+	+ 10:15 01.12.08	In operation
	14	04	715	25.12.06	03.04.07		23.2	+	+ 10:15 01.12.08	In operation
	15	00	716	25.12.06	12.10.07		23.2	+	+ 03:15 01.12.08	In operation
III	17	-1	718	26.10.07	04.12.07		13.2	+	+ 04:00 01.12.08	In operation
	18	-3	724	25.09.08	26.10.08		2.2	+	+ 06:00 01.12.08	In operation
	19	03	720	26.10.07	25.11.07		13.2	+	+ 07:45 01.12.08	In operation
	20	02	719	26.10.07	27.11.07		13.2	+	+ 09:15 01.12.08	In operation
	21	-1	725	25.09.08	05.11.08		2.2	+	+ 10:15 01.12.08	In operation
	22	-3	726	25.09.08	13.11.08		2.2	+	+ 10:14 01.12.08	In operation
	23	03	714	25.12.05	31.08.06		35.2	+	+ 10:15 01.12.08	In operation
	24	02	713	25.12.05	31.08.06		35.2	+	+ 02:28 01.12.08	In operation

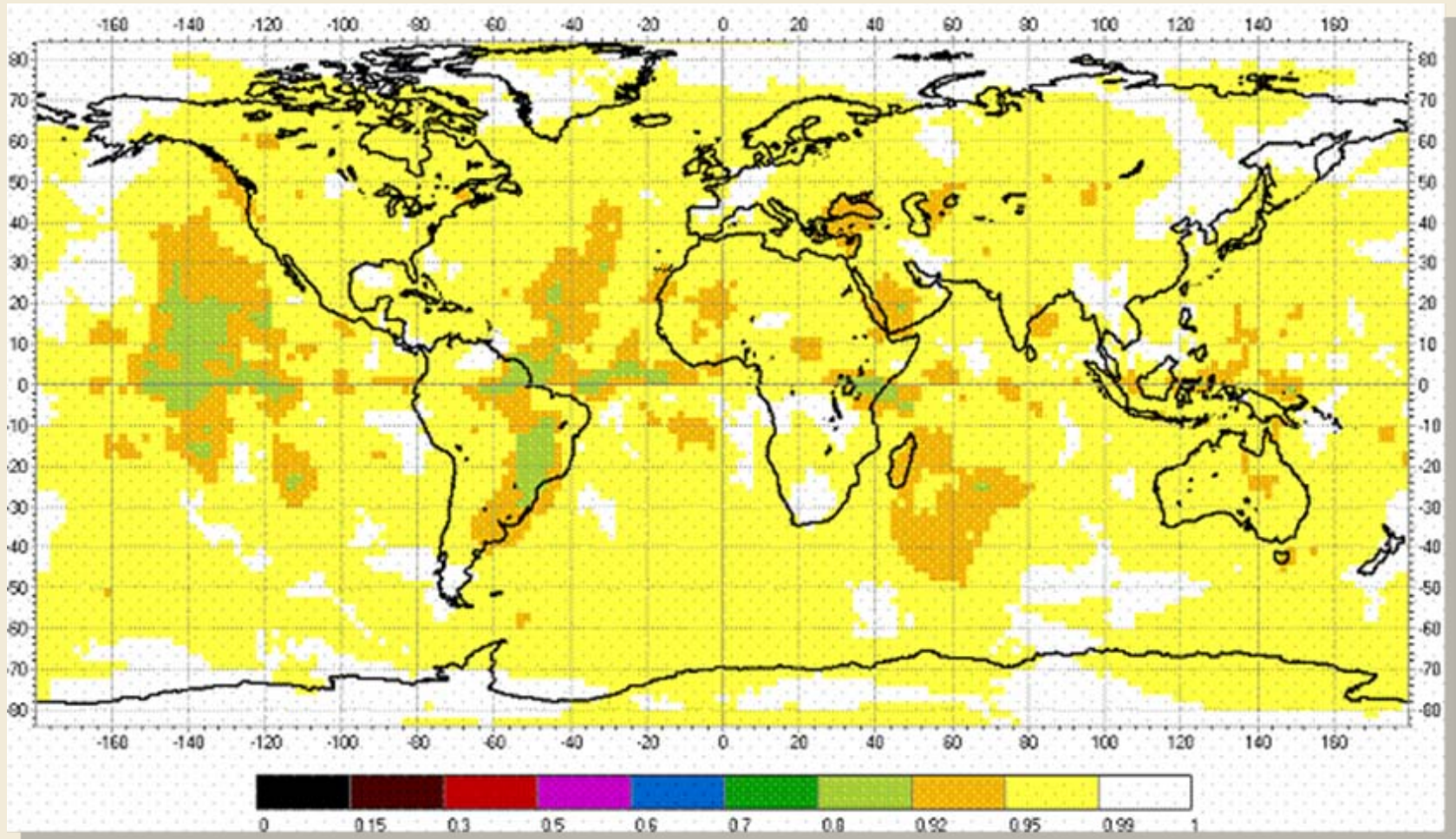
<b>Total satellites in constellation</b>	<b>19 SC</b>
Operational	14 SC
In commissioning phase	3 SC
In maintenance	1 SC
In decommissioning phase	1 SC

Probability that  $\text{GDOP} < 5$  for mask angle of  $25^\circ$  (a case for urban canyon)





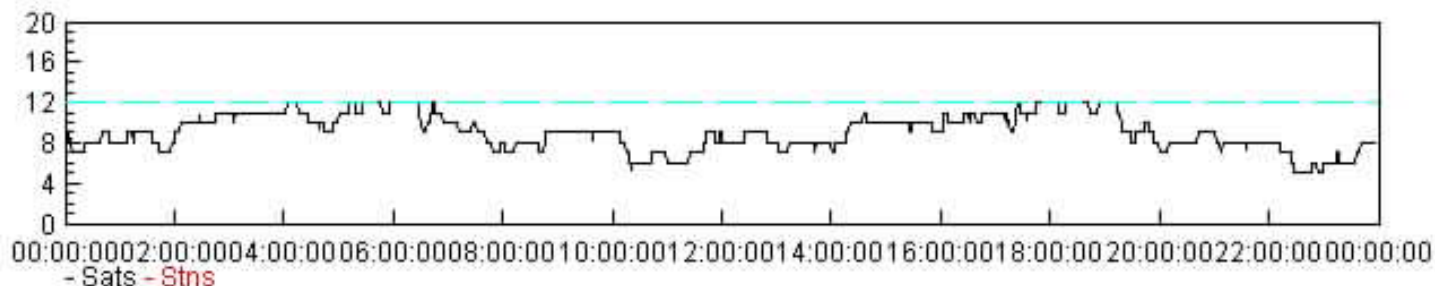
Probability that  $\text{GDOP} < 5$  for mask angle of  $25^\circ$  (a case for urban canyon)





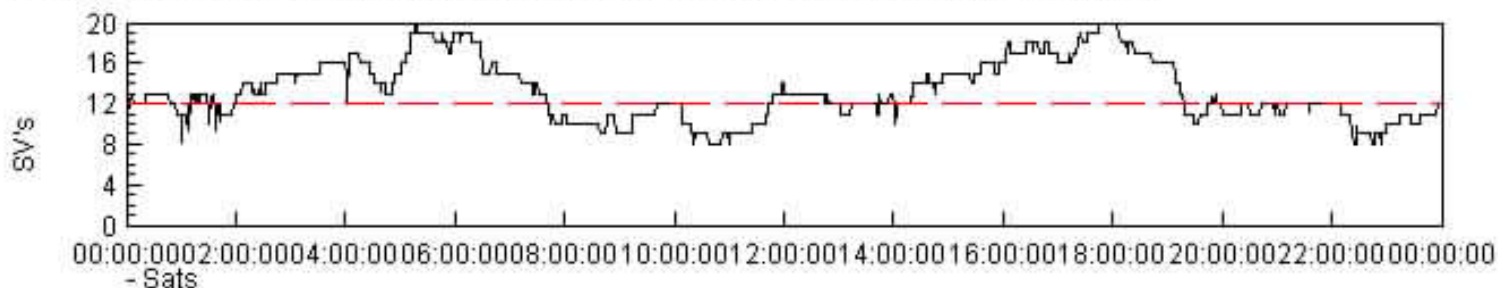
# Number of Satellites Available, Elevation Mask 8°

Satellites: Sats: Min:5.00, Max:12.00, Mean:9.07, SD:1.78, 2SD:3.58, Count:172602



GPS: Mean: 9 satellites

Satellites & Stations: Sats: Min:8.00, Max:20.00, Mean:13.29, SD:2.93, 2SD:5.85, Count:85967



GPS+GLONASS: Mean: 13 satellites





# Fugro G2 Development





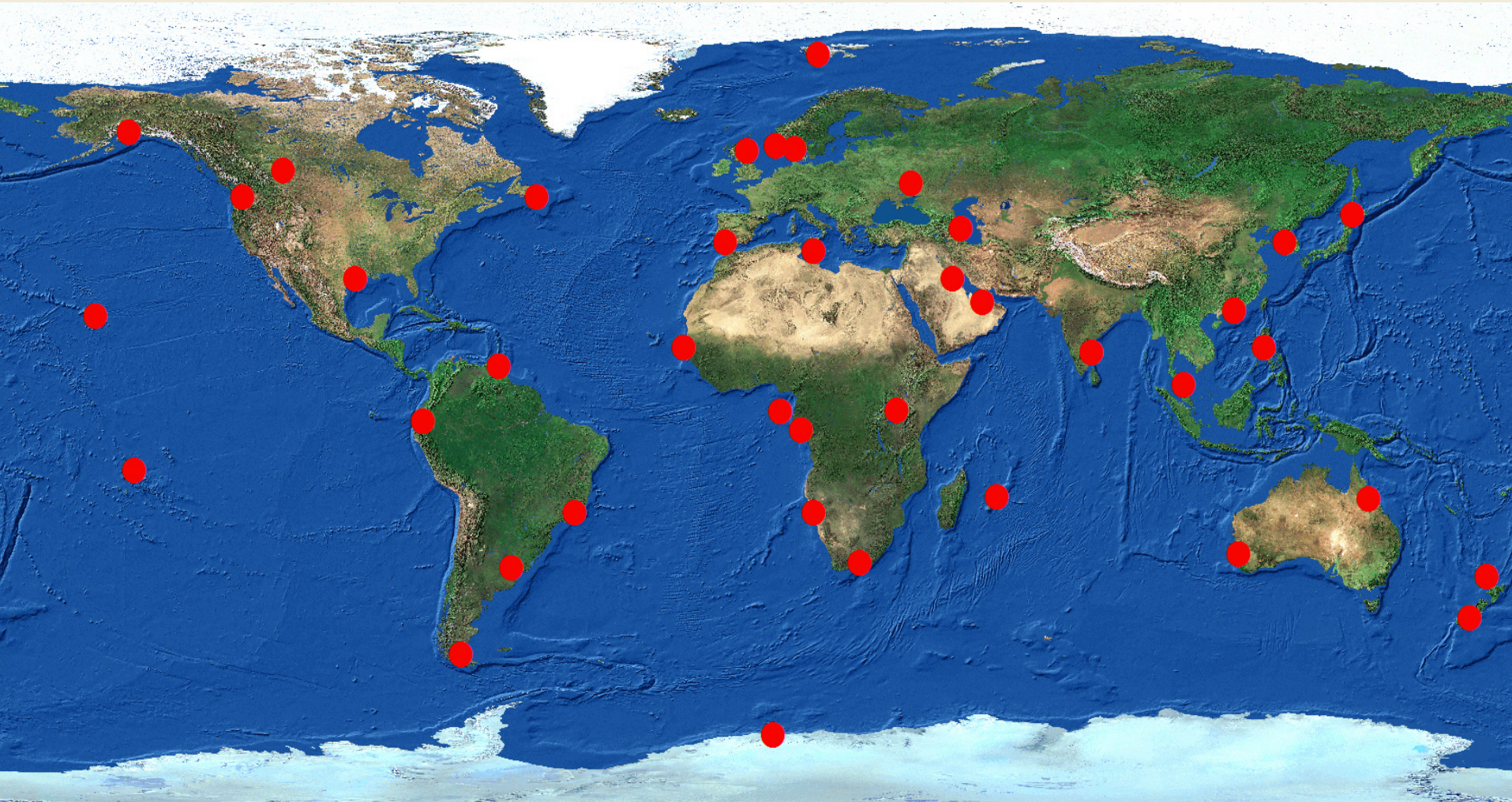
What is G2 ?

# **GPS & GLONASS PPP Utilising Fugro Derived Corrections**



- Key Milestones:
  - The G2 concept was conceived around year 2000
  - A development contract was signed February 2003 with ESA and the development started
  - The decision to include GLONASS was made in October 2004
  - G2 test signal on the air from February 2008
  
- Fugro's Motivation
  - Precise orbit and clock is the future
  - Fugro develops this technology further
    - Solution Independent of JPL
    - Addition of GLONASS





Currently about 35 stations





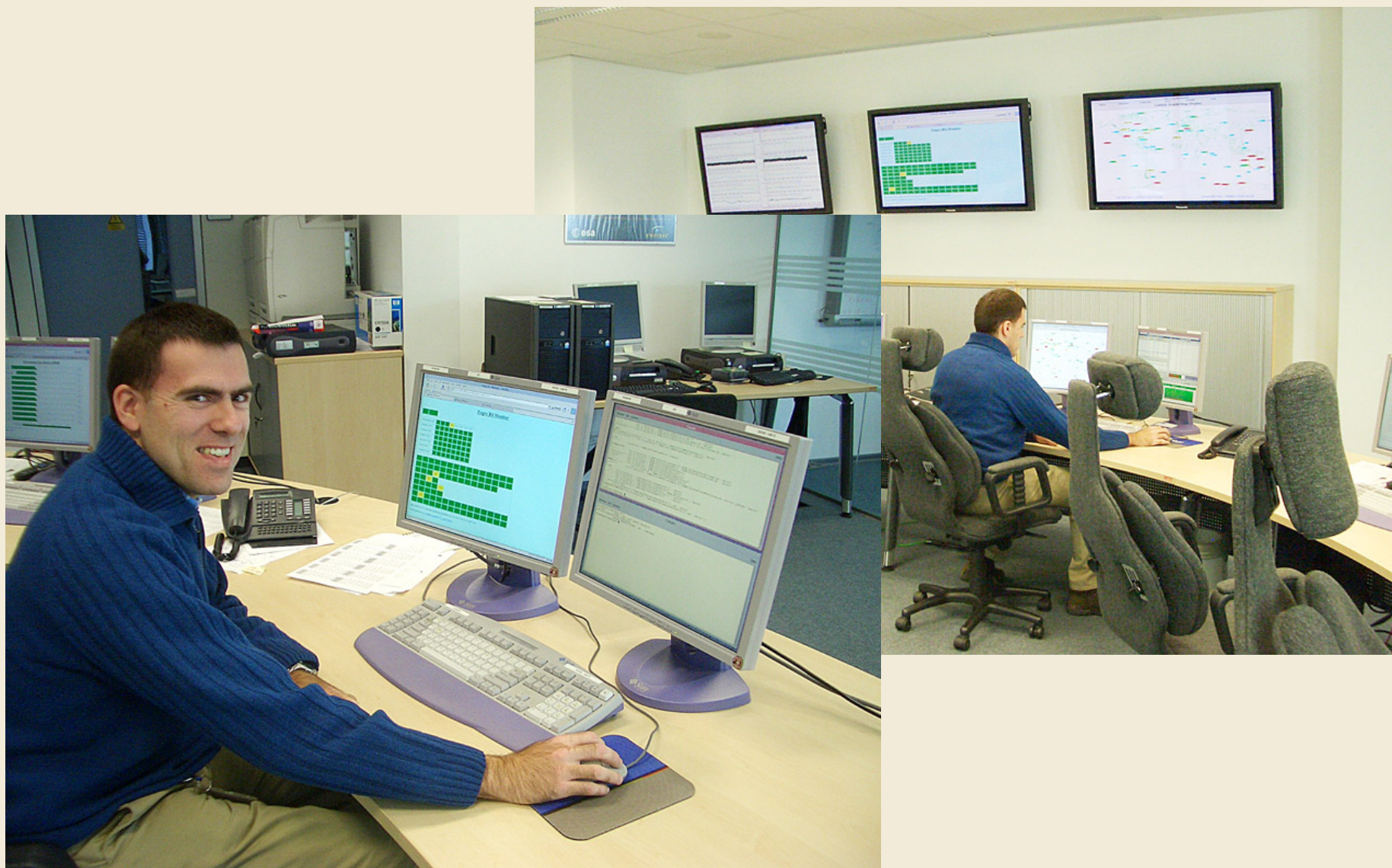
# Operations and Monitoring Centre, Oslo







# Support Team at ESA



# Advantages of Combined GNSS Systems

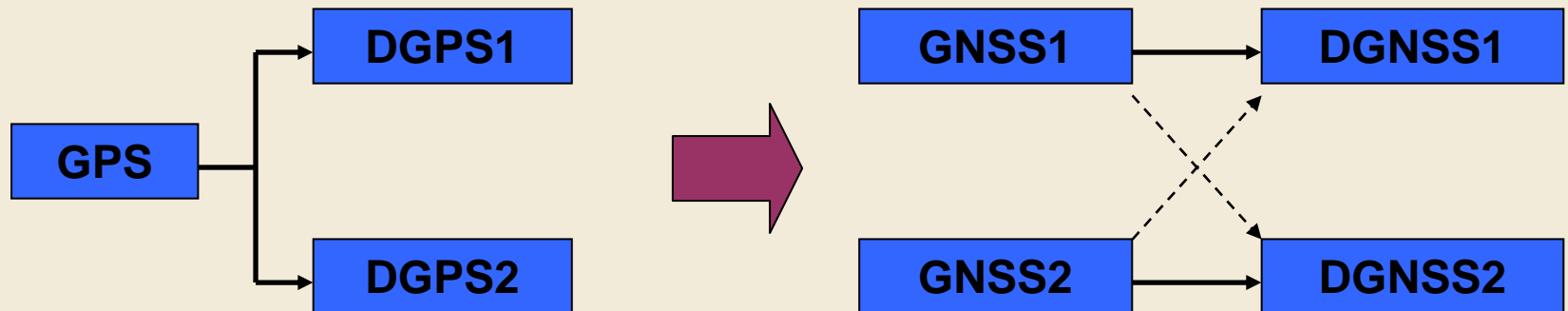




# Improved Performance with Several GNSS

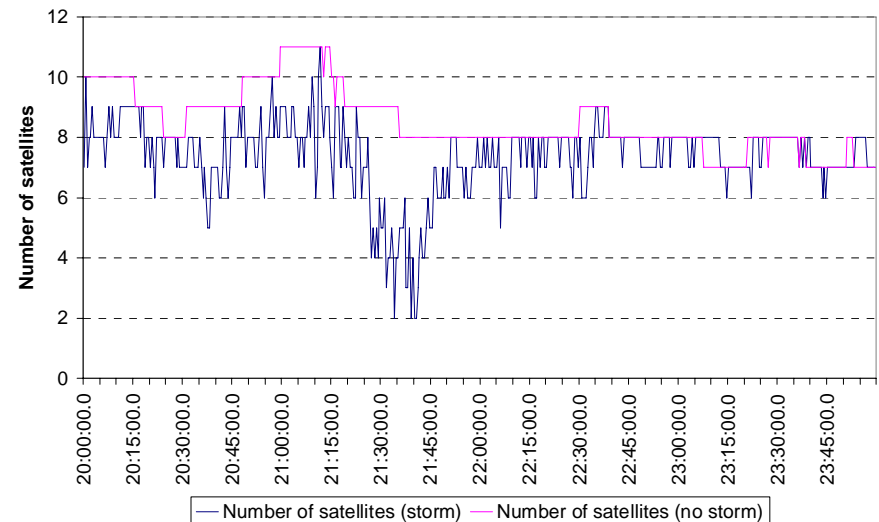
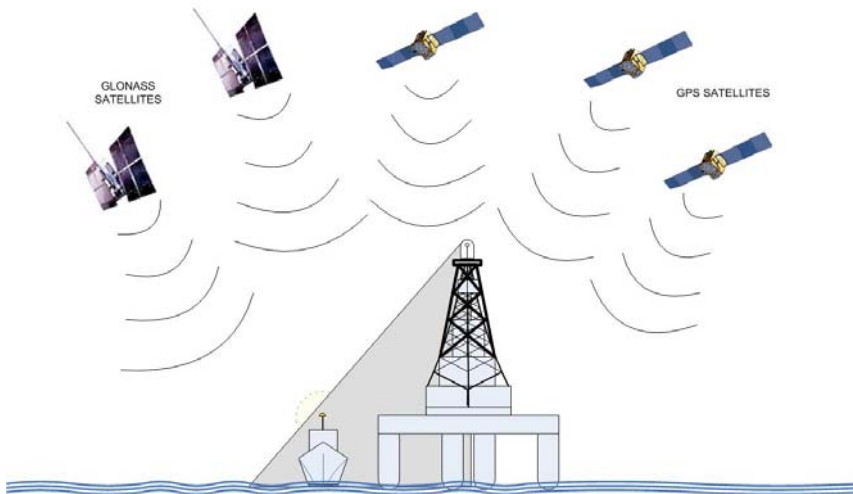
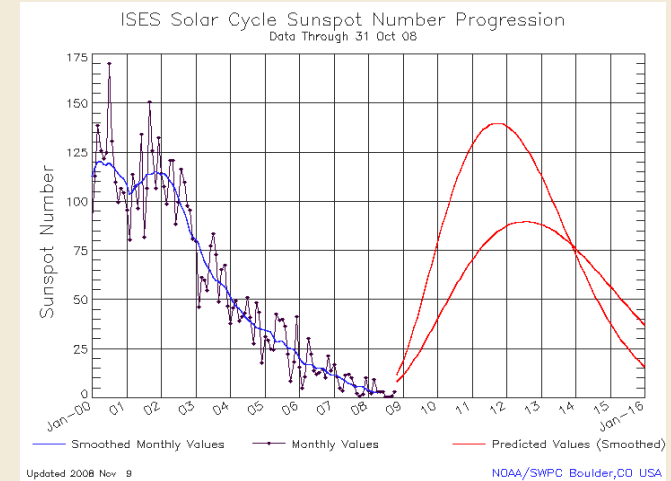
- Independence
  - When more systems become fully operational, they can be used as independent systems in safety critical applications
- Availability
  - Combined systems will improve availability of satellite navigation in situations where parts of the sky are obscured. This will be the case close to oil rigs, during ionospheric scintillations etc.
- Reliability
  - Increased redundancy of data (additional lines of position) will help to identify bad measurements
- Accuracy
  - Improved accuracy with more satellites (improved geometry)
  - Improved convergence time in phase based decimeter level systems

- Independence
  - Today GPS is used in all satellite navigation reference systems
  - When more systems become fully operational, they can be used as independent systems in safety critical applications

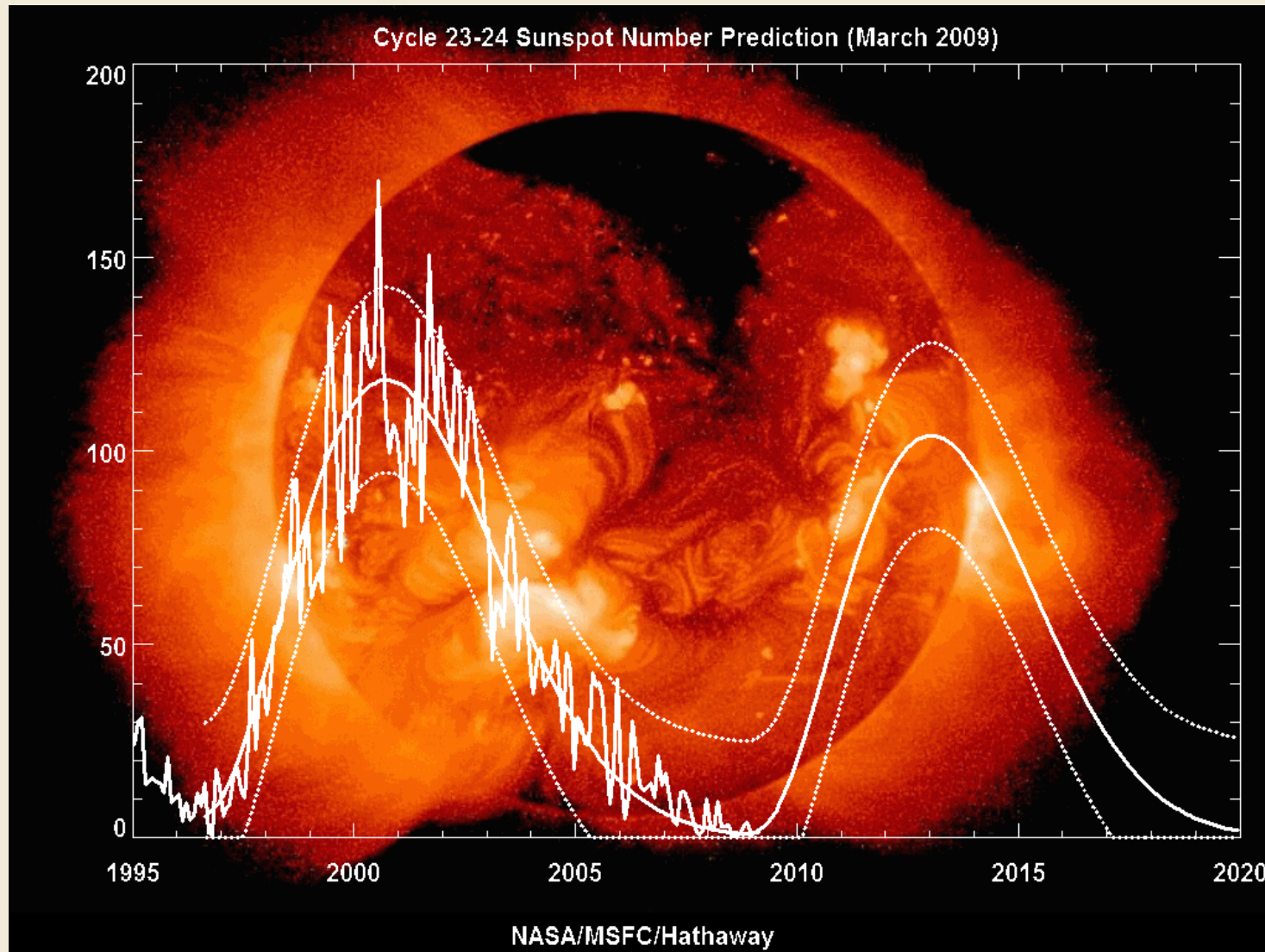




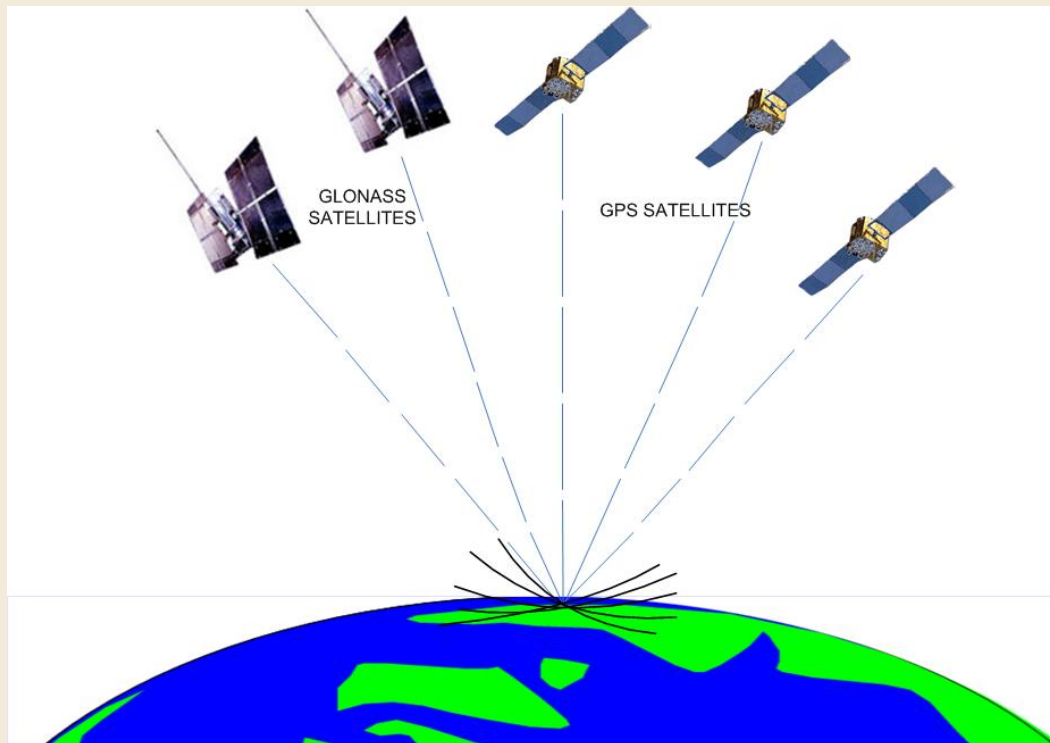
- Availability
  - Combined systems will improve availability of satellite navigation in situations where parts of the sky are obscured. This will be the case close to oil rigs, during ionospheric scintillations etc.







- Reliability
  - Increased redundancy of data (additional lines of position) will help to identify bad measurements
    - RAIM = Receiver Autonomous Integrity Monitoring
    - Also a part of UKOOA Guidelines





## **Orbit and Clock versus DGPS:**

1. Requires fewer reference stations than differential (global coverage)
2. One set of correction data valid everywhere
3. No baseline ("distance to ref. station") dependent errors
4. Independence from local reference station performance
5. Better correction data during ionospheric storms
6. High redundancy and robustness



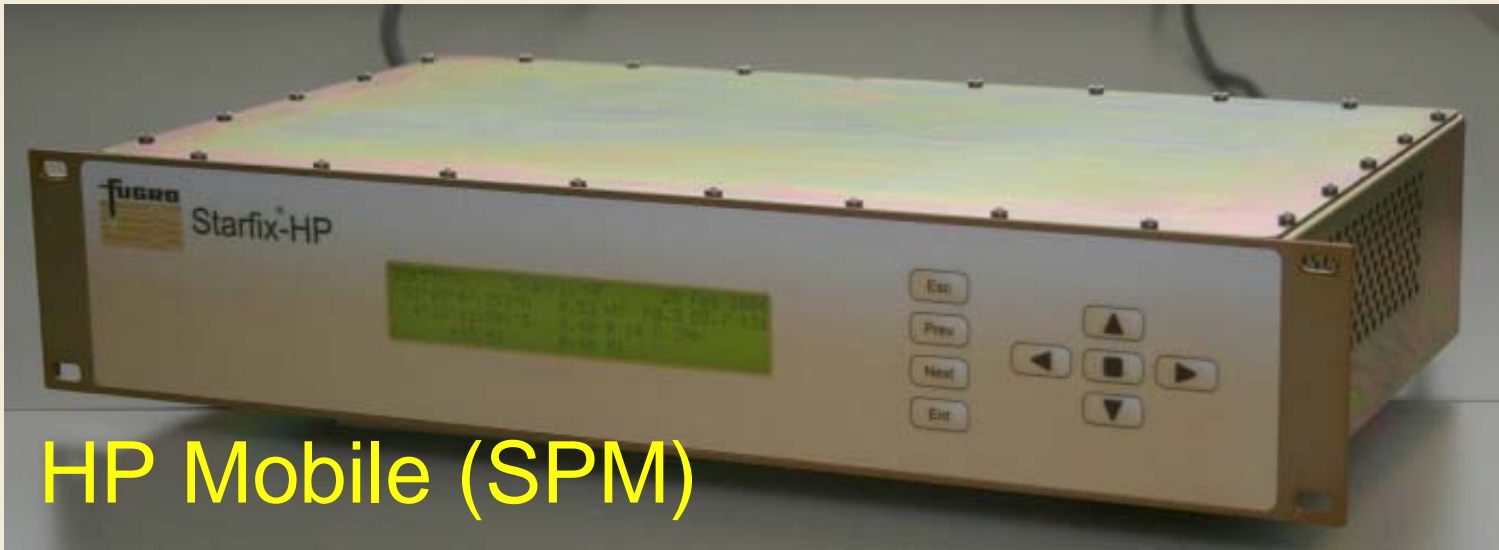


# Products, Trials and Results





# Survey / Positioning Hardware Implementation



HP Mobile (SPM)

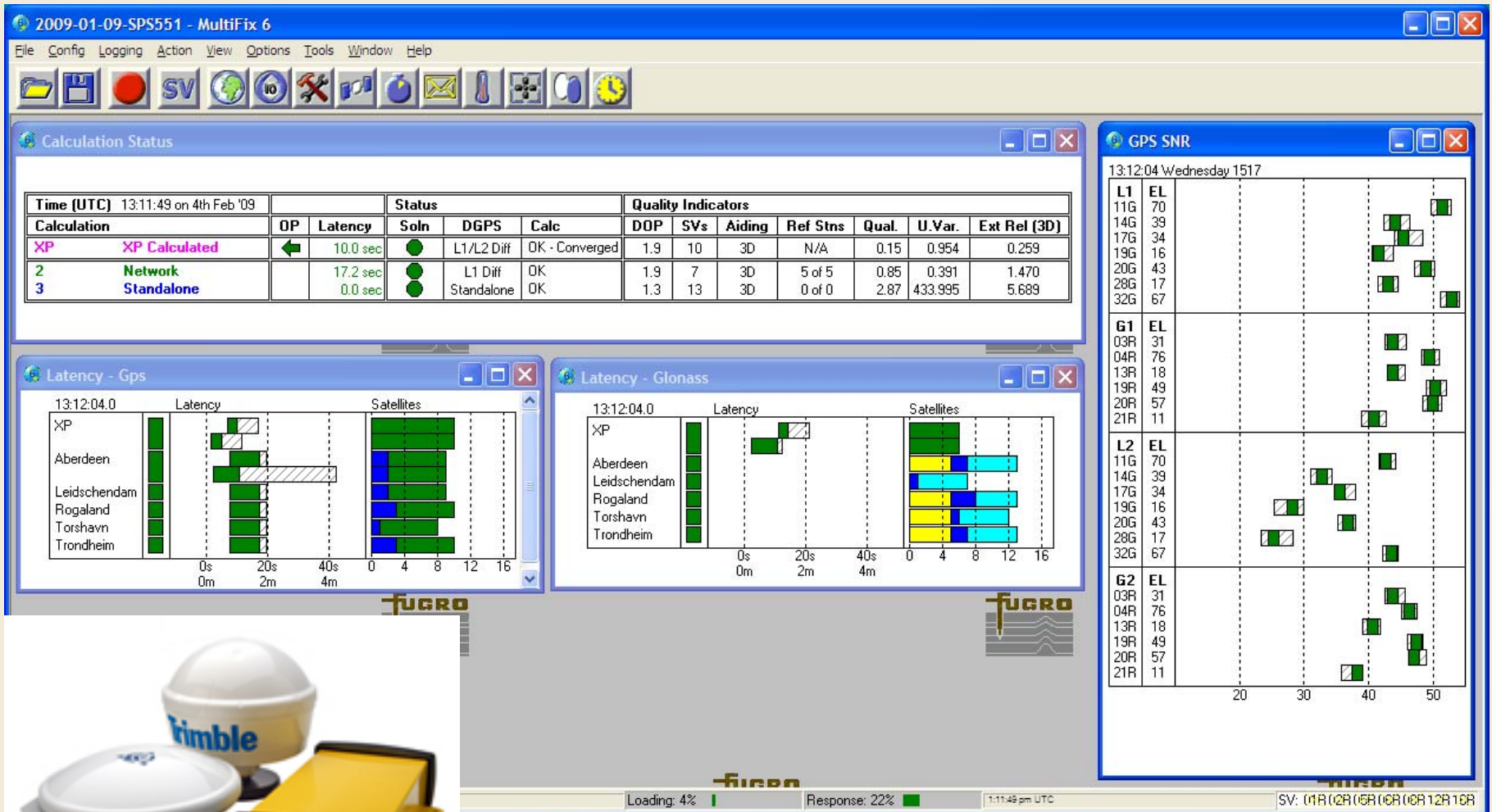


StarPack





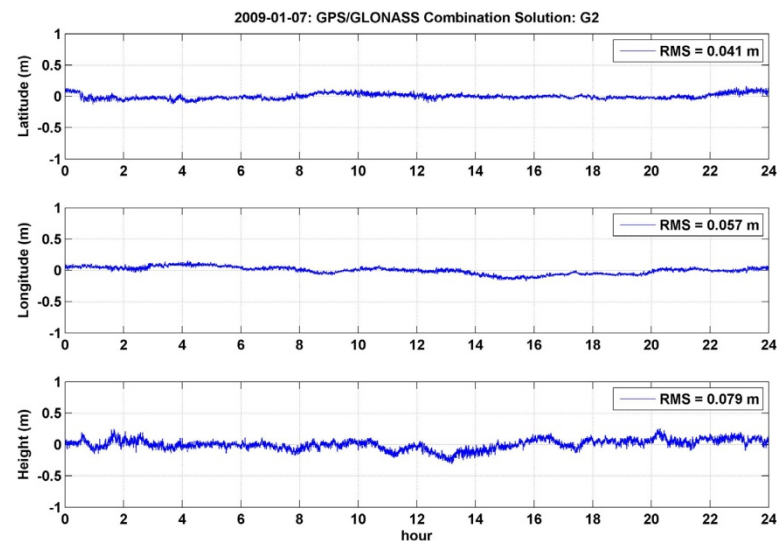
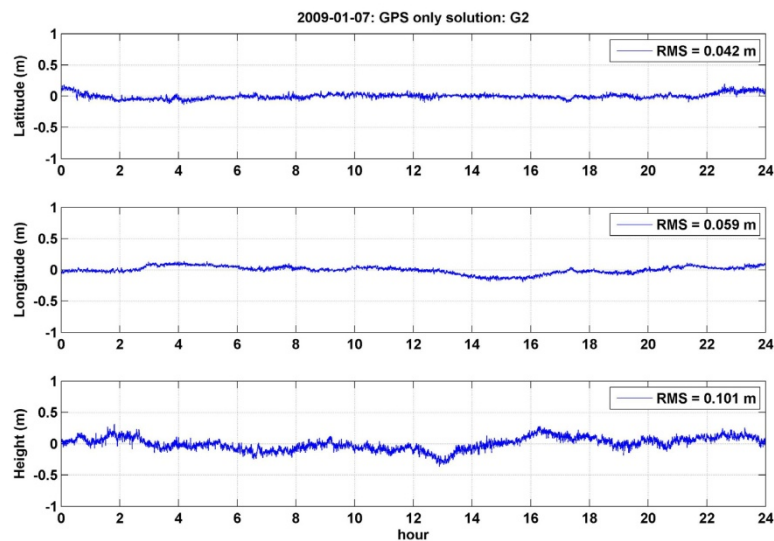
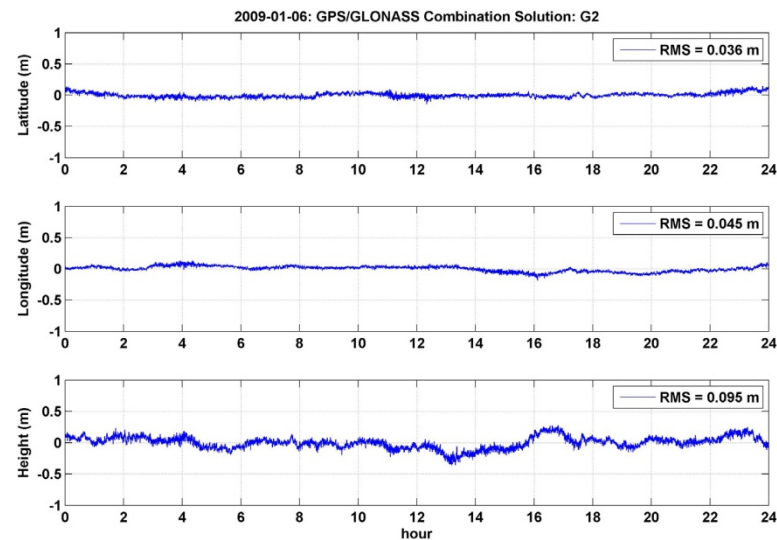
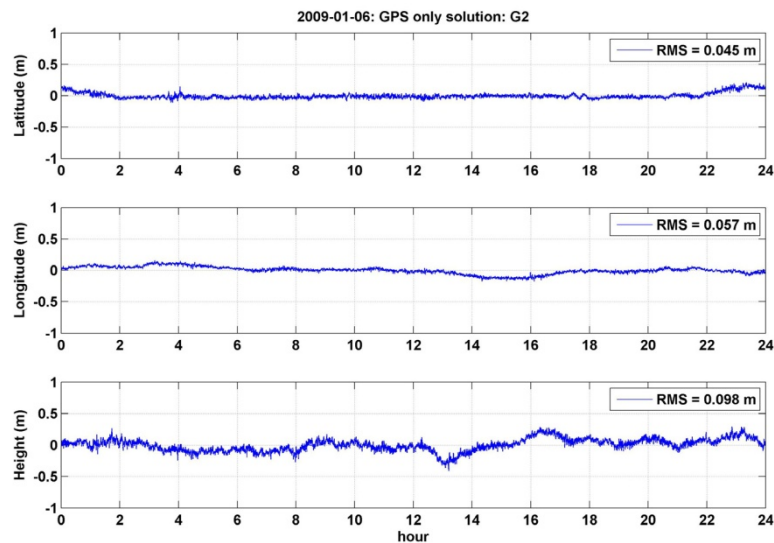
# Survey / Positioning Software Implementation



## MultiFix6 Software



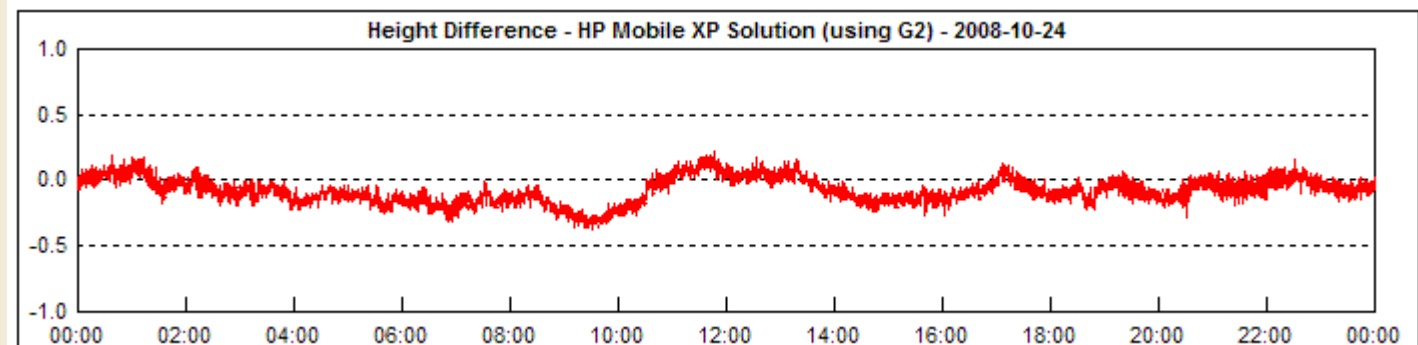
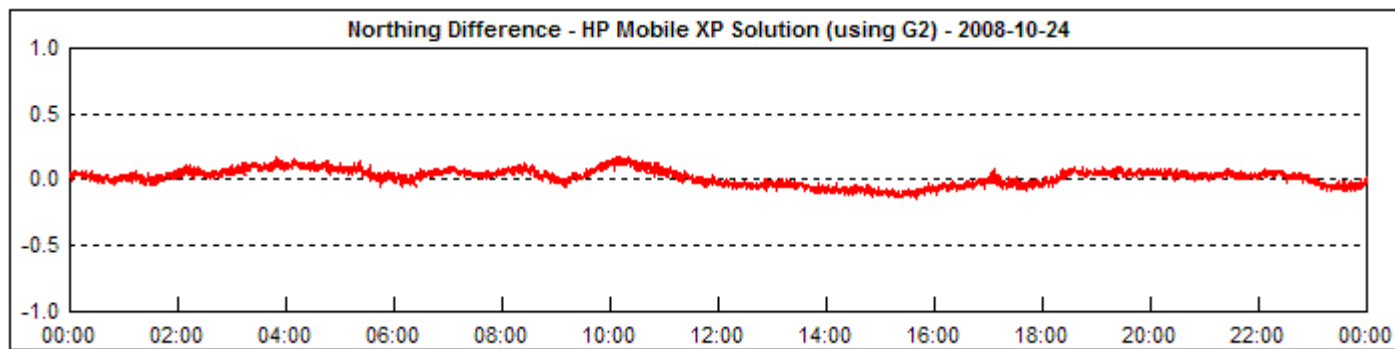
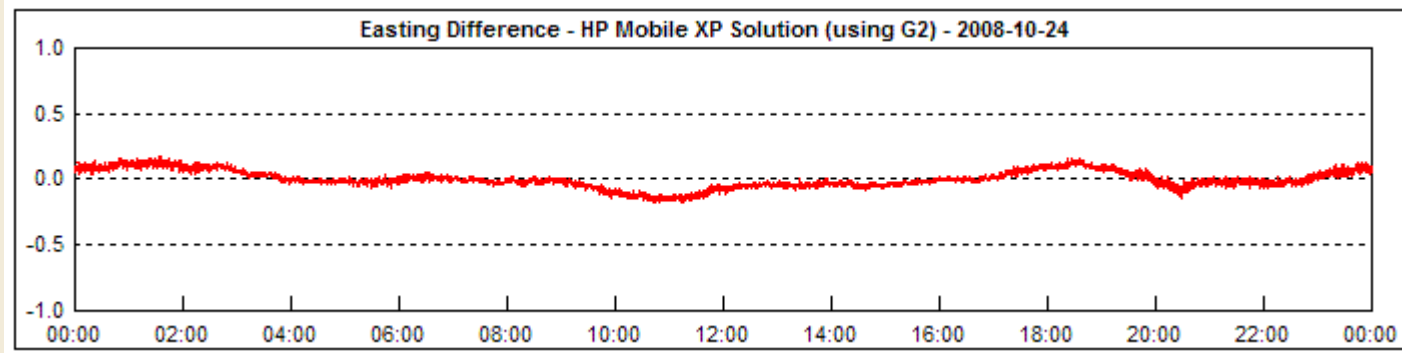
# January 2009 – GPS Versus GPS & GLONASS





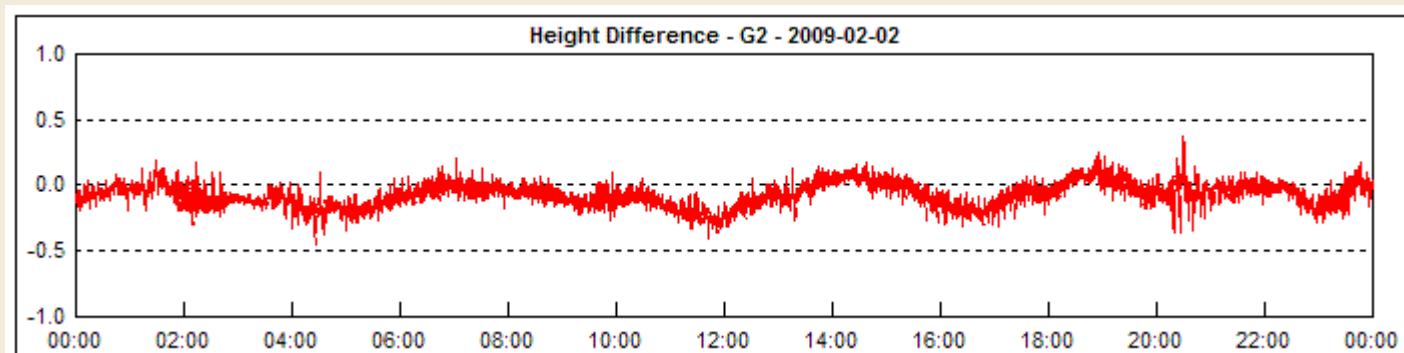
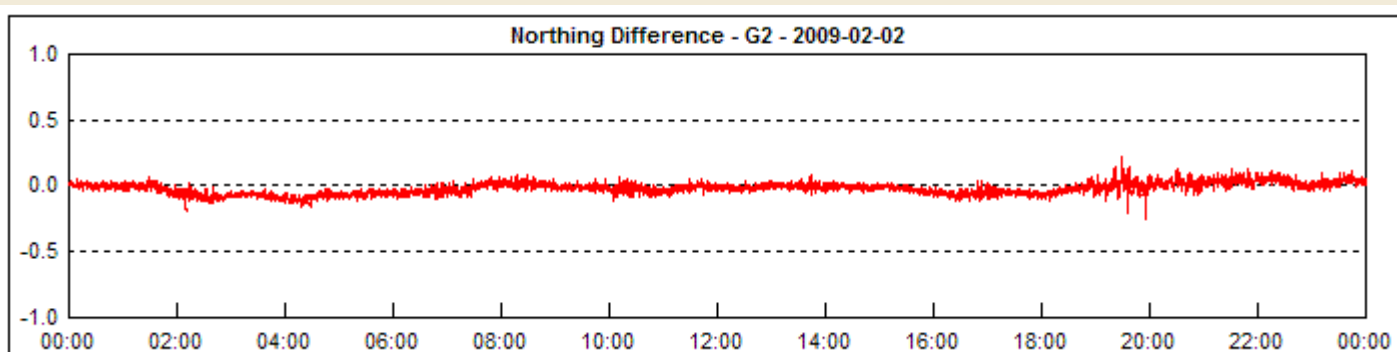
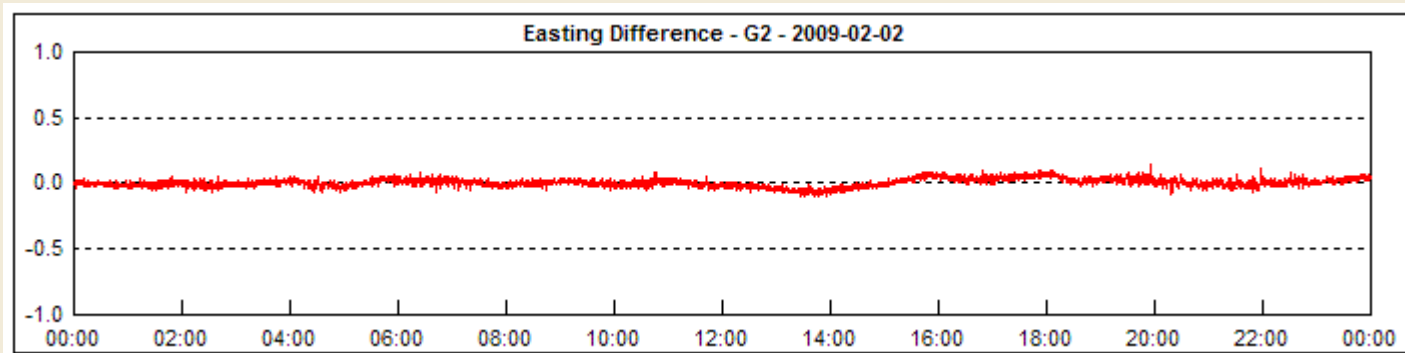


# Early System Performance – October 2008





# System Performance – February 2009





## G2 Performance Summary

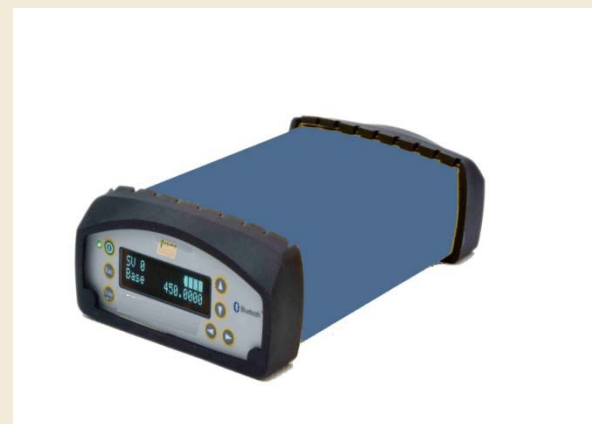
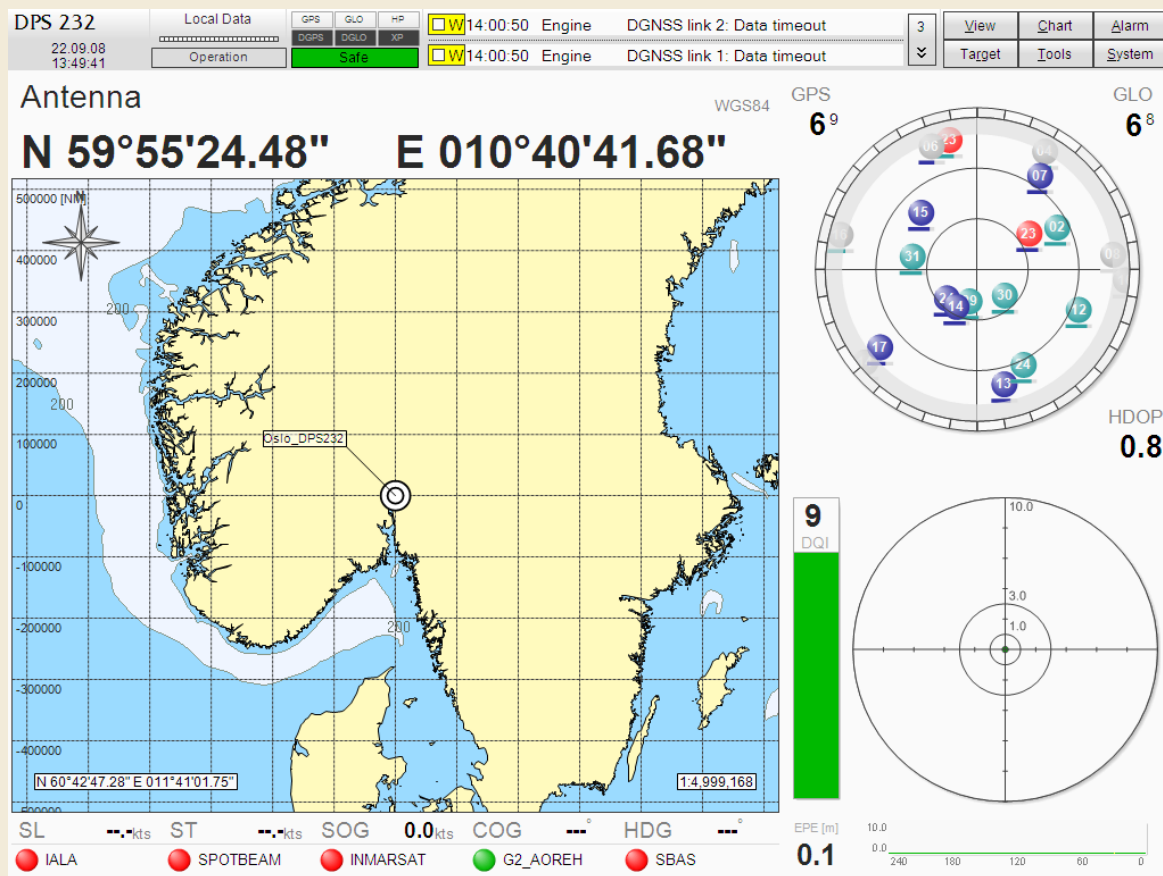
	Accuracy (95%)			Precision (95%)		
Date	Easting	Northing	Height	Easting	Northing	Height
24 Oct 2008	-0.001 m	0.017 m	0.088 m	0.126 m	0.110 m	0.233 m
2 Feb 2009	0.003 m	-0.023 m	-0.075 m	0.055 m	0.088 m	0.221 m

Accuracy (Reliability):      Offset from a “known” geodetic point.

Precision:                      Spread of data.



## Kongsberg Seatex DPS 232 Dual Frequency GPS / GLONASS Uses new Fugro correction service.



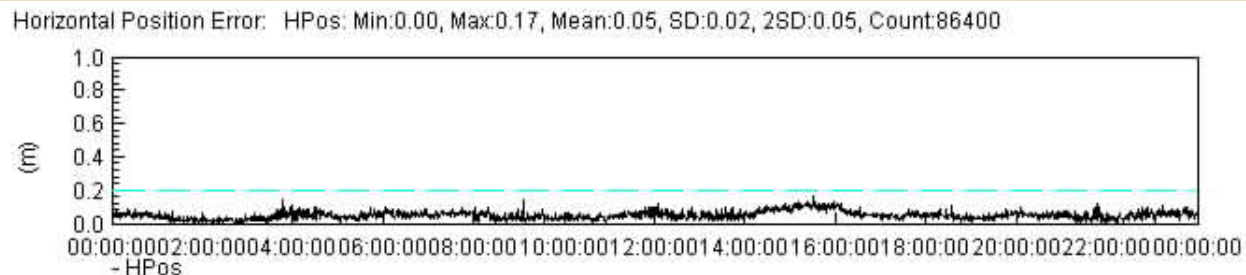
Fugro Branded  
Trimble 9200-G2



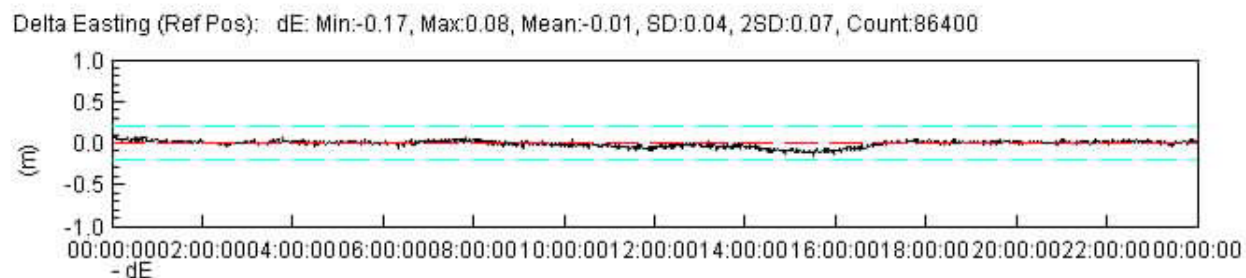


# Kongsberg Seatex DPS232 Tests, 6 January 2009

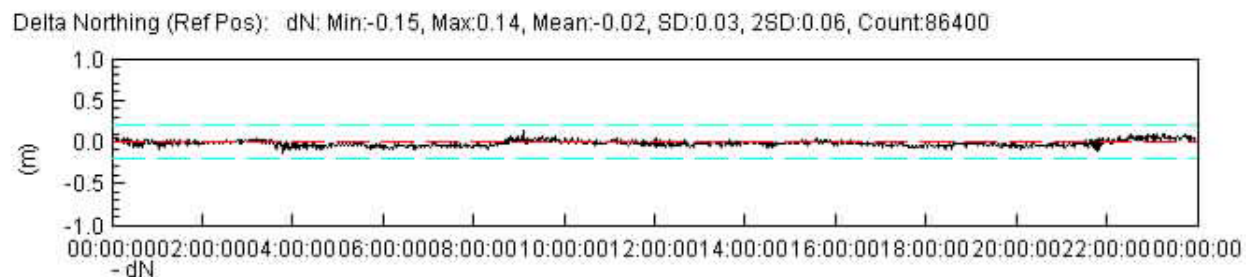
Horizontal Error



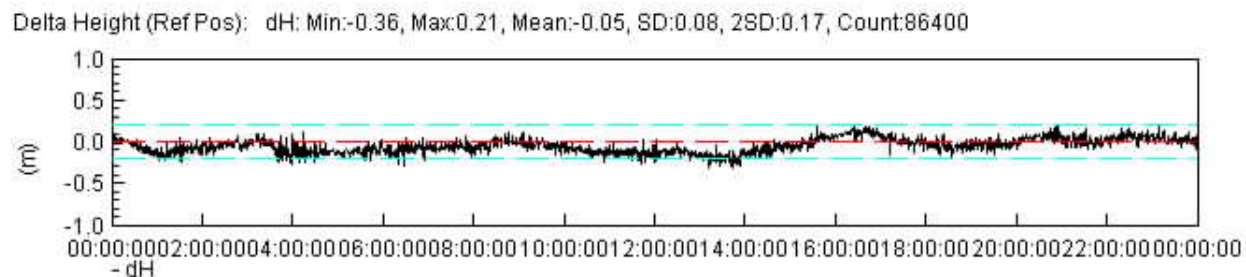
East Error



North Error



Height Error



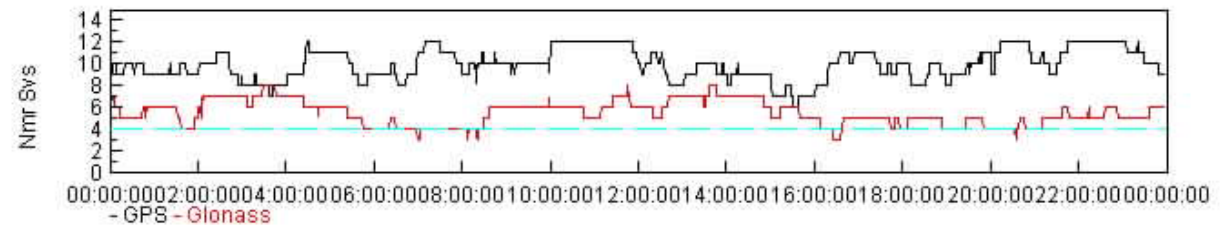


# Kongsberg Seatex DPS232 Tests, 6 January 2009

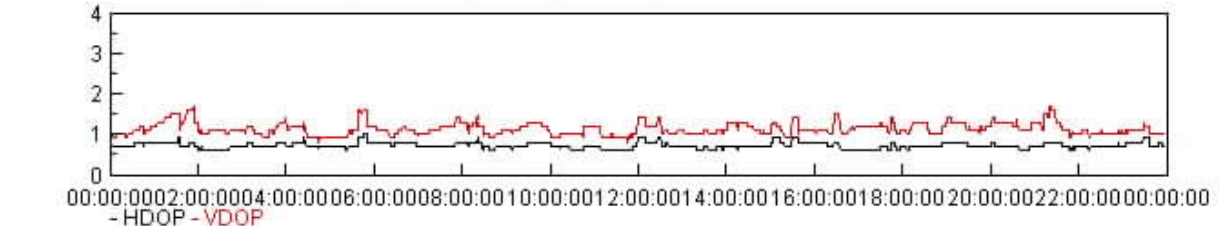
No of Satellites

NMEA GSA, DPS232\_5.00A33\_509364\_AFSat

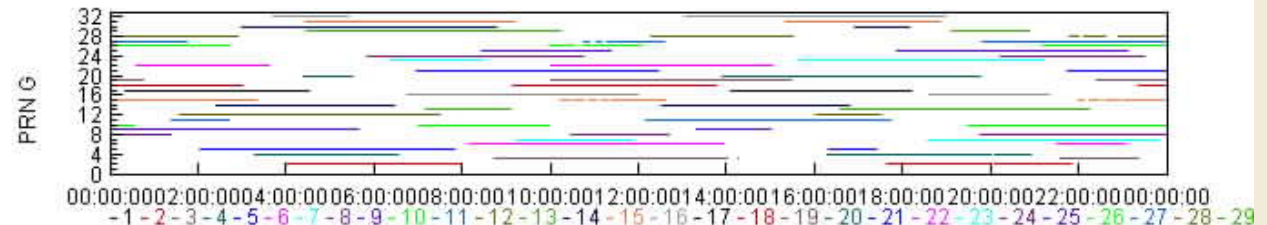
Number of Satellites: GPS: Min:6.00, Max:12.00, Mean:9.91, SD:1.40, 2SD:2.80, Count:86400



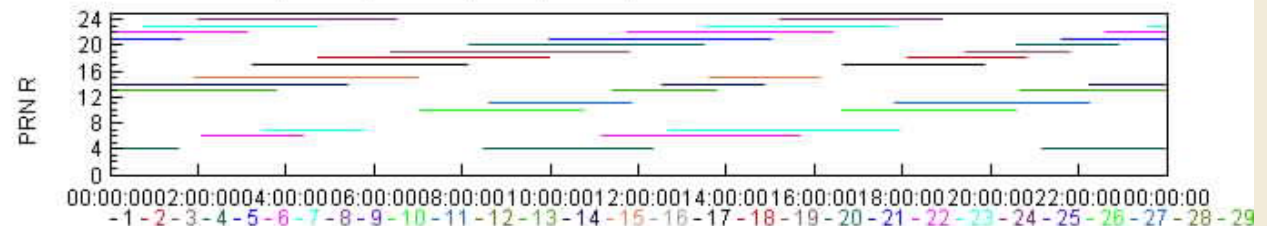
DOPS: HDOP: Min:0.60, Max:1.00, Mean:0.72, SD:0.08, 2SD:0.15, Count:86400



GPS PRNs: 1: Min:NA, Max:NA, Mean:NA, SD:NA, 2SD:NA, Count:0



Glonass PRNs: 1: Min:NA, Max:NA, Mean:NA, SD:NA, 2SD:NA, Count:0



GPS PRNs

GLONASS PRNs

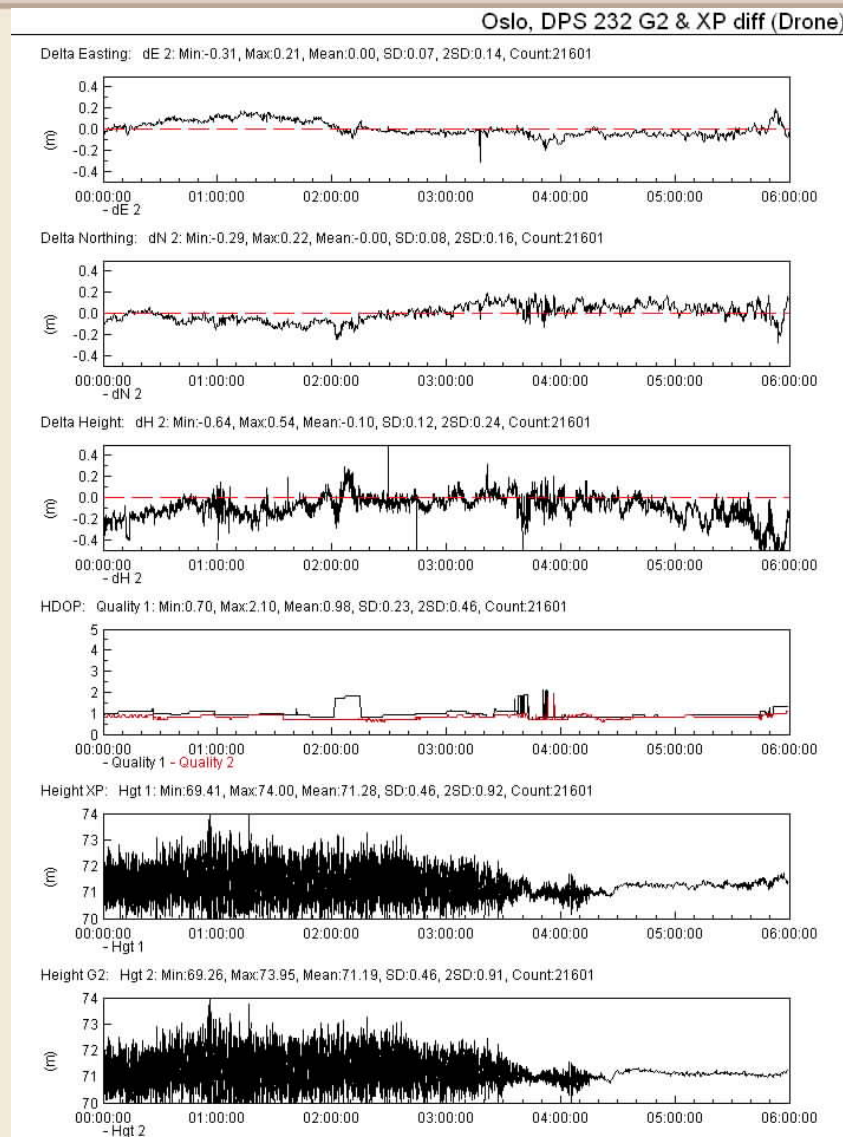


# Dynamic Trials onboard Bourbon Topaz

- Seatex DPS 232 in G2 mode
- Seatex DPS 232 in XP mode
- Both connected to the same antenna



- Difference between G2 and XP in Easting, northing and height, 6 hours
- HDOP in G2 (2) and XP (1)
- Height in XP and HP (2-3 m heave at sea, at harbour 04:30)

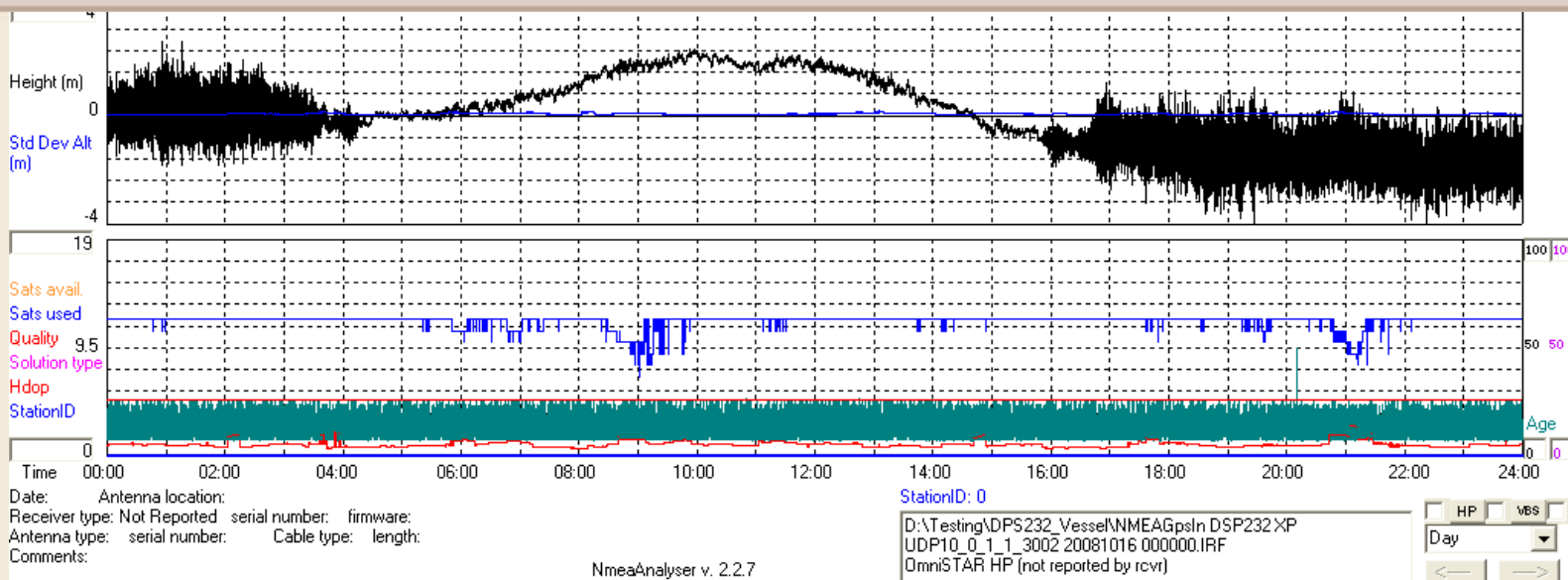




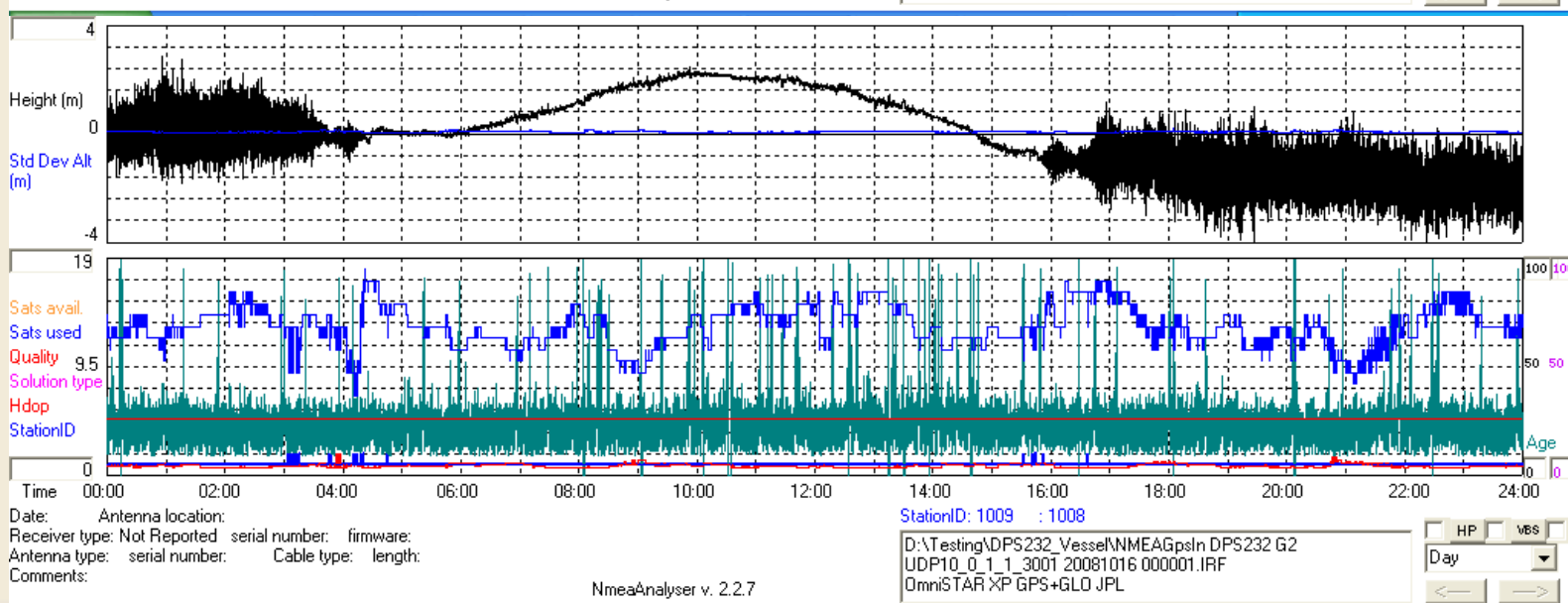


# Bourbon Topaz – 16 October 2008

XP, 24hours

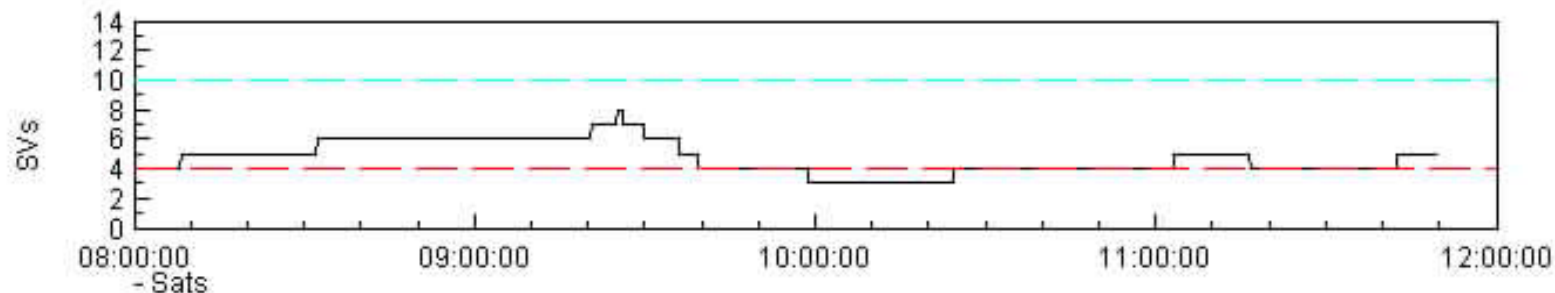


G2, 24 hours

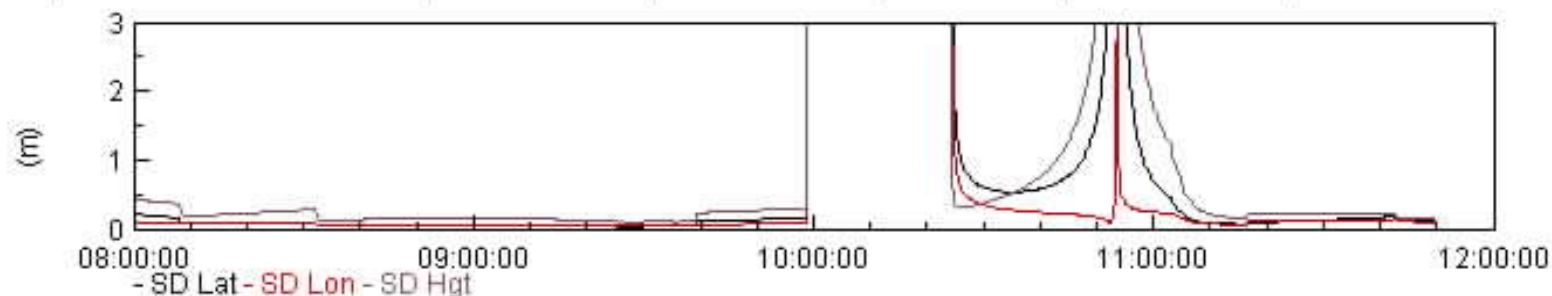


## XP,EHP,GPS,NetR5,AD491,AOREH,EI>25 (59°55'24.4561"N 10°40'41.7806"E)

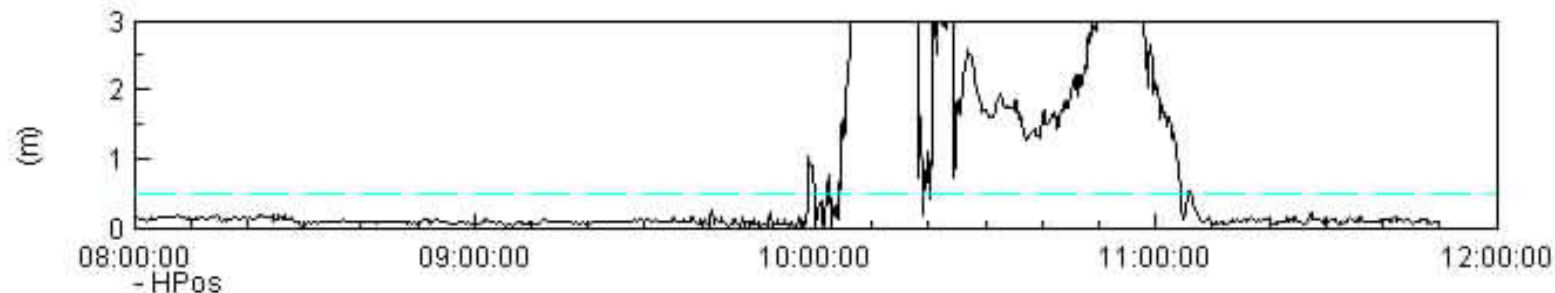
Satellites: Sats: Min:3.00, Max:8.00, Mean:4.87, SD:0.99, 2SD:1.98, Count:12556



Reported SDs: SD Lat: Min:0.03, Max:2253059.00, Mean:14874.41, SD:105665.37, 2SD:211330.73, Count:12556



Horizontal Position error: HPos: Min:0.00, Max:1352.65, Mean:1.26, SD:17.48, 2SD:34.97, Count:12556

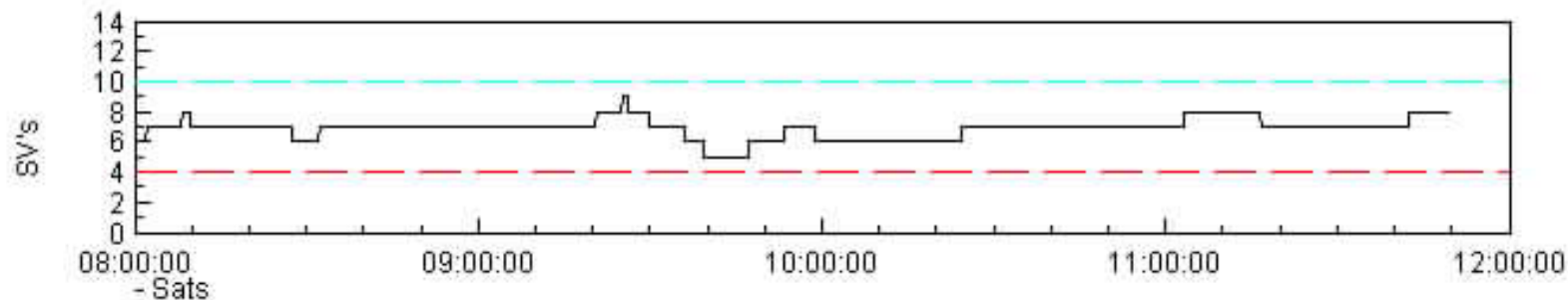




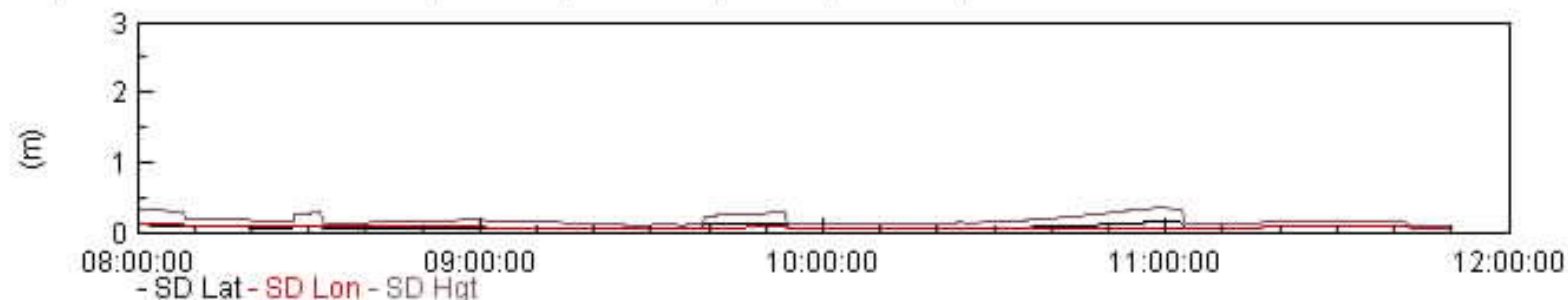
# GPS & GLONASS, Elevation Mask 25°

EHP, GPS+GLO, NetR5, AD491, AOREH, EI>25 (59°55'24.4561"N 10°40'41.7806"E)

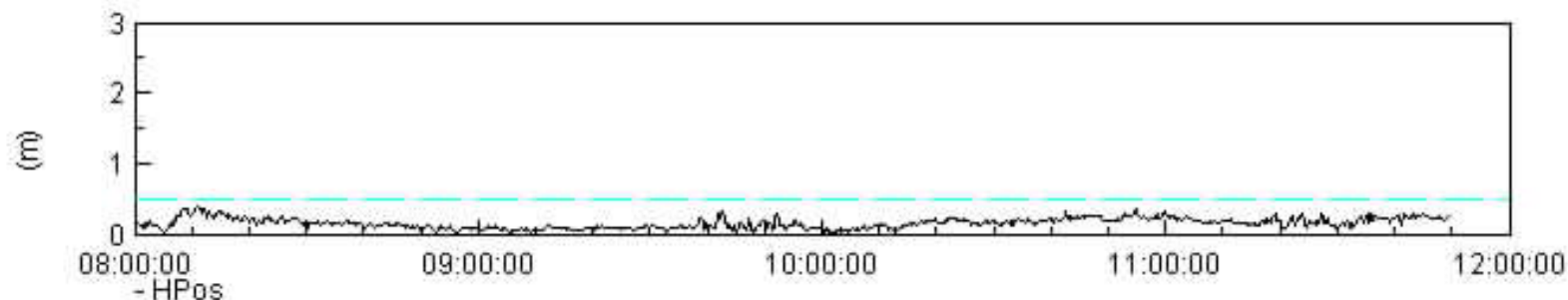
Satellites: Sats: Min:5.00, Max:9.00, Mean:6.89, SD:0.67, 2SD:1.34, Count:13738



Reported SDs: SD Lat: Min:0.04, Max:0.14, Mean:0.07, SD:0.03, 2SD:0.05, Count:13738



Horizontal Position Error: HPos: Min:0.00, Max:0.40, Mean:0.15, SD:0.07, 2SD:0.14, Count:13738

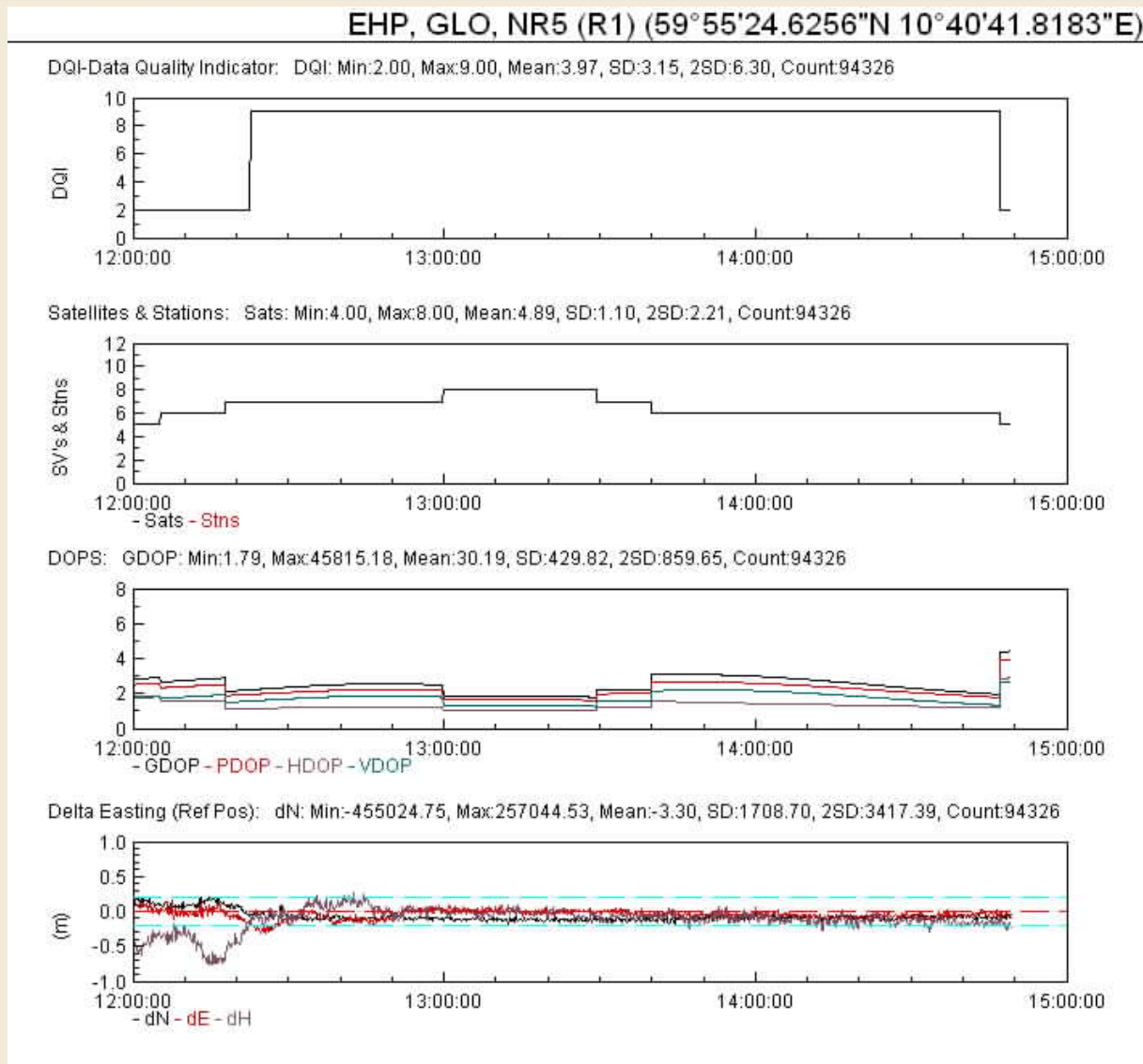




# GLONASS Only Coverage

During periods with enough GLONASS satellites, the solution is at the decimetre level using only GLONASS satellites.

dN = North error  
dE = East Error  
dH = Height error





# What does the Future have in Store ?



## ▪ *Open Access*

- Free to air; Mass market; Simple positioning  
(L1 single frequency: 15m H, 35m V, dual frequency: 4m H, 8 m V)

## ▪ *Commercial*

- Encrypted; High accuracy; Guaranteed service

## ▪ *Safety of Life*

- Unencrypted; Integrity; Authentication of signal  
(12 m HAL, 20 m VAL, others service level available)

## ▪ *Search and Rescue*

- Near real-time; Precise; Return link feasible

## ▪ *Public Regulated*

- Encrypted; Integrity; Continuous availability

OS



CS



SOL



PRS



- China has filed for frequencies at ITU (International Telecommunications Union)
- 27 Satellites MEO, 21500 km, 55 deg
- 5 Satellites in Geostationary Orbit, 35786 km
- 3 Satellites Inclined Geostationary Orbit, 35786 km, 55 deg
- Similar frequencies as Galileo
- 10 meter accuracy
- Start launching two satellites 2008 (Geostationary)
- Continuation of the military "Beidou"

## CHINA VIEW

[www.chinaview.cn](http://www.chinaview.cn)

[Chinese\(Big5\)](#) | [Spanish](#) | [French](#) | [Russian](#) | [Arabic](#)

[Gov.cn](#) | [Photo Gallery](#) | [Opinions](#) | [Weather](#) | [About China](#) | [About Us](#)

[Latest News :](#)    percent in Octo

---

### China starts to build own satellite navigation system

www.chinaview.cn 2006-11-02 12:52:53

BEIJING, Nov. 2 (Xinhua) -- China has started to build its own satellite navigation system, called Compass.

The planned network, also referred to as Beidou in Chinese, entails the launching of five geostationary Earth orbit (GEO) and 30 medium Earth orbit (MEO) satellites, informed sources said here Thursday.

China plans to launch two Compass navigation satellites at the beginning of next year. The system is expected to cover China and parts of neighbouring countries by 2008 before being developed into a global constellation, according to the sources.

The system will provide two navigation services. The Open Service is designed to provide users with positioning accuracy within 10 meters, velocity accuracy with 0.2 meter per second and timing accuracy within 50 nanoseconds.

The Authorized Service will offer "safer" positioning, velocity, timing communications for authorized users.

China is willing to cooperate with other countries in developing its satellite navigation industry to allow the Compass system to operate with other global satellite positioning systems, the source said.

China has sent three Compass navigation test satellites into orbit in Oct. and Dec. of 2000 and in May 25 of 2003.

Aerospace experts said the existing three-satellite Compass navigation system has played an important role in offering efficient navigation and positioning services for sectors including survey, telecommunications, transportation, meteorology, forest fire prevention, disaster forecast and public security.



- All elements of G2 developed and implemented by Fugro
- Uses correction data from Fugro's proprietary reference station network, both GPS and GLONASS.
- 10 cm accuracy (95%) almost independent of location.
- Improved Performance with Multiple GNSS
  - Independence
  - Availability
  - Reliability
  - Accuracy
- Within a few years up 120 GNSS satellites could be available for navigation and positioning.



